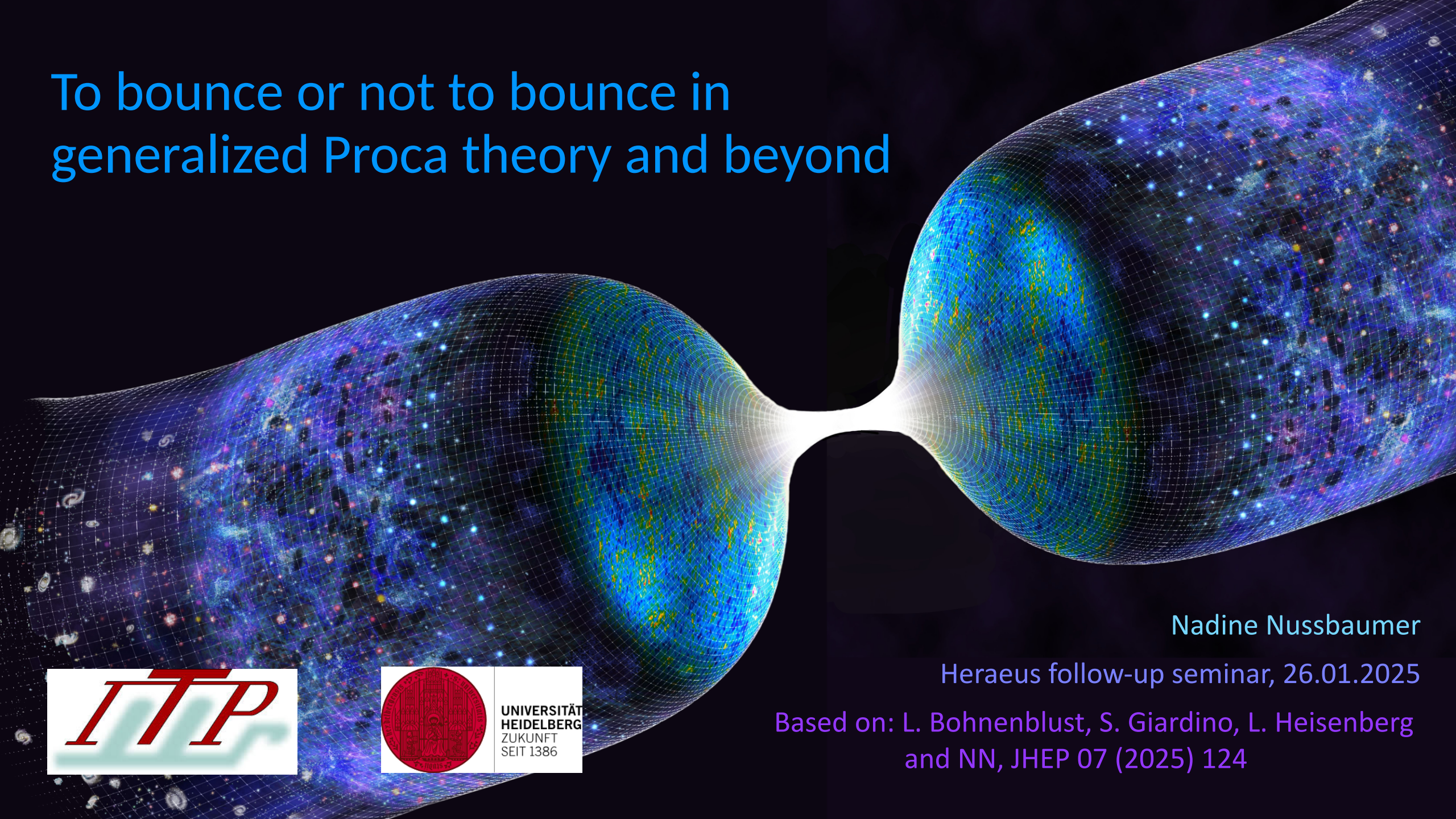


# To bounce or not to bounce in generalized Proca theory and beyond



Nadine Nussbaumer

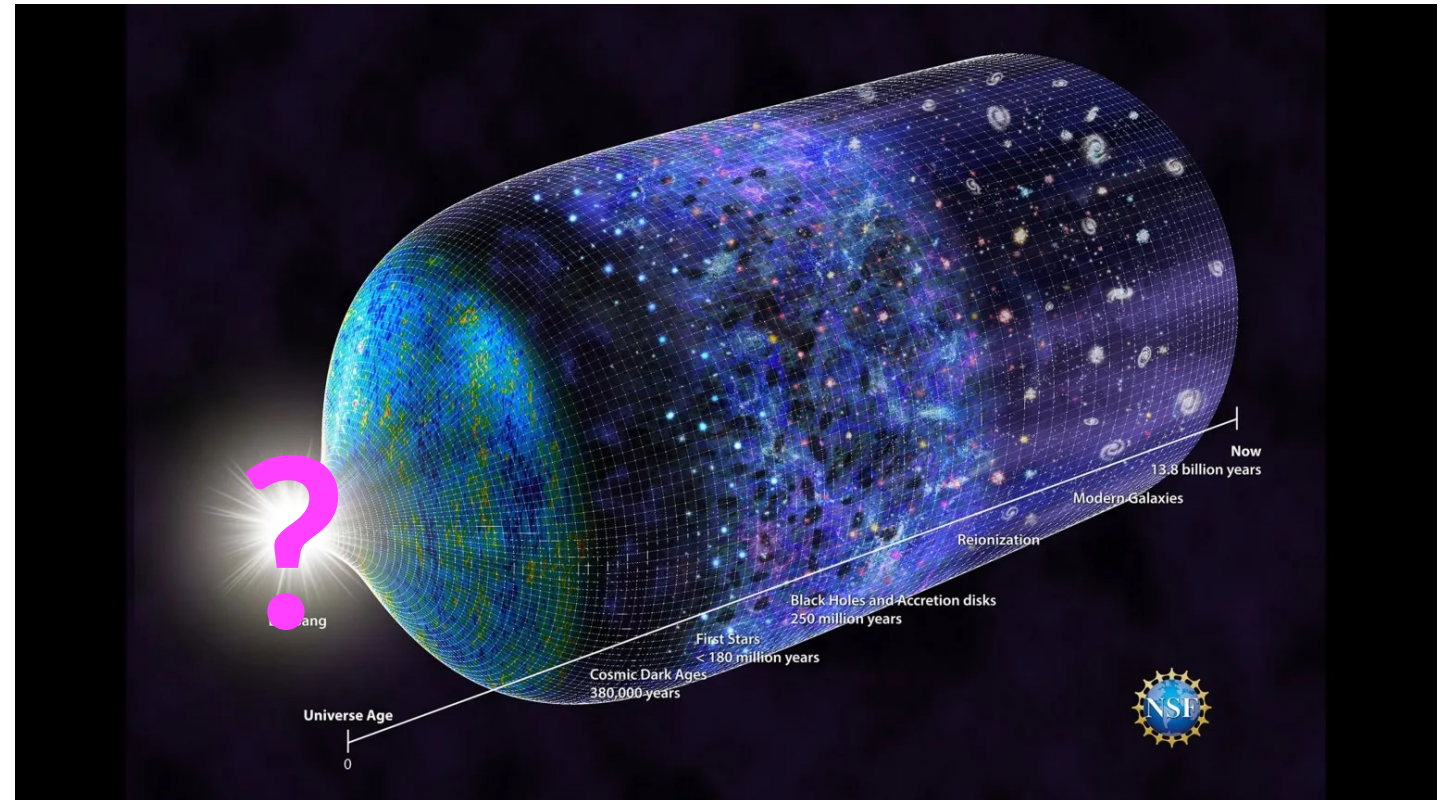
Heraeus follow-up seminar, 26.01.2025

Based on: L. Bohnenblust, S. Giardino, L. Heisenberg  
and NN, JHEP 07 (2025) 124



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# Why bounces?



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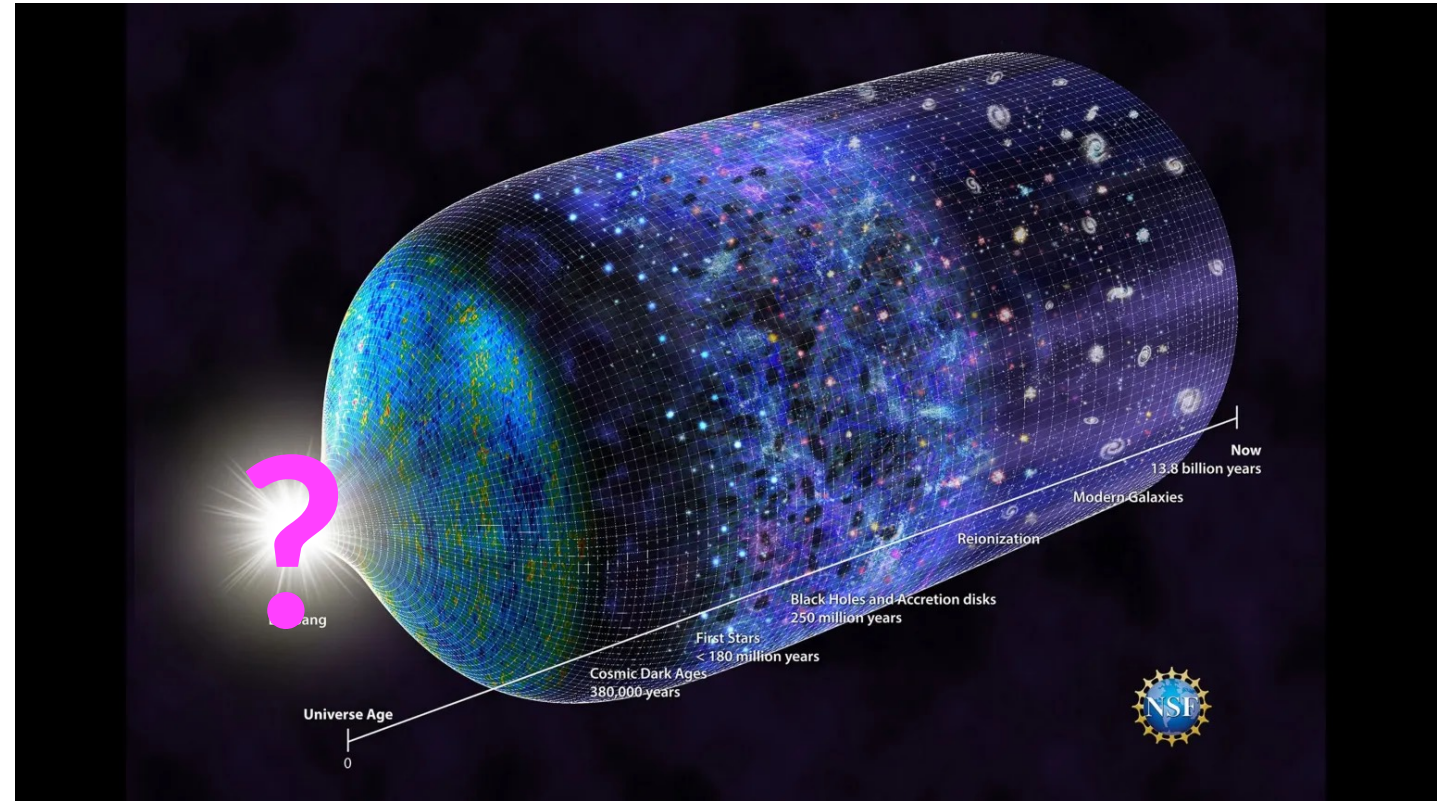
# Why bounces?

- Alternative to inflation
- Inflation has a **singularity** and a **trans-Planckian** problem

Initial singularity  $a(t_i) = 0$

If #e-foldings slightly higher than needed -> modes start in trans-Planckian regime

=> problems can be avoided by classical, non-singular bounces



D. Battefeld et al., 2015  
R. Brandenberger et al., 2017

National Science Foundation

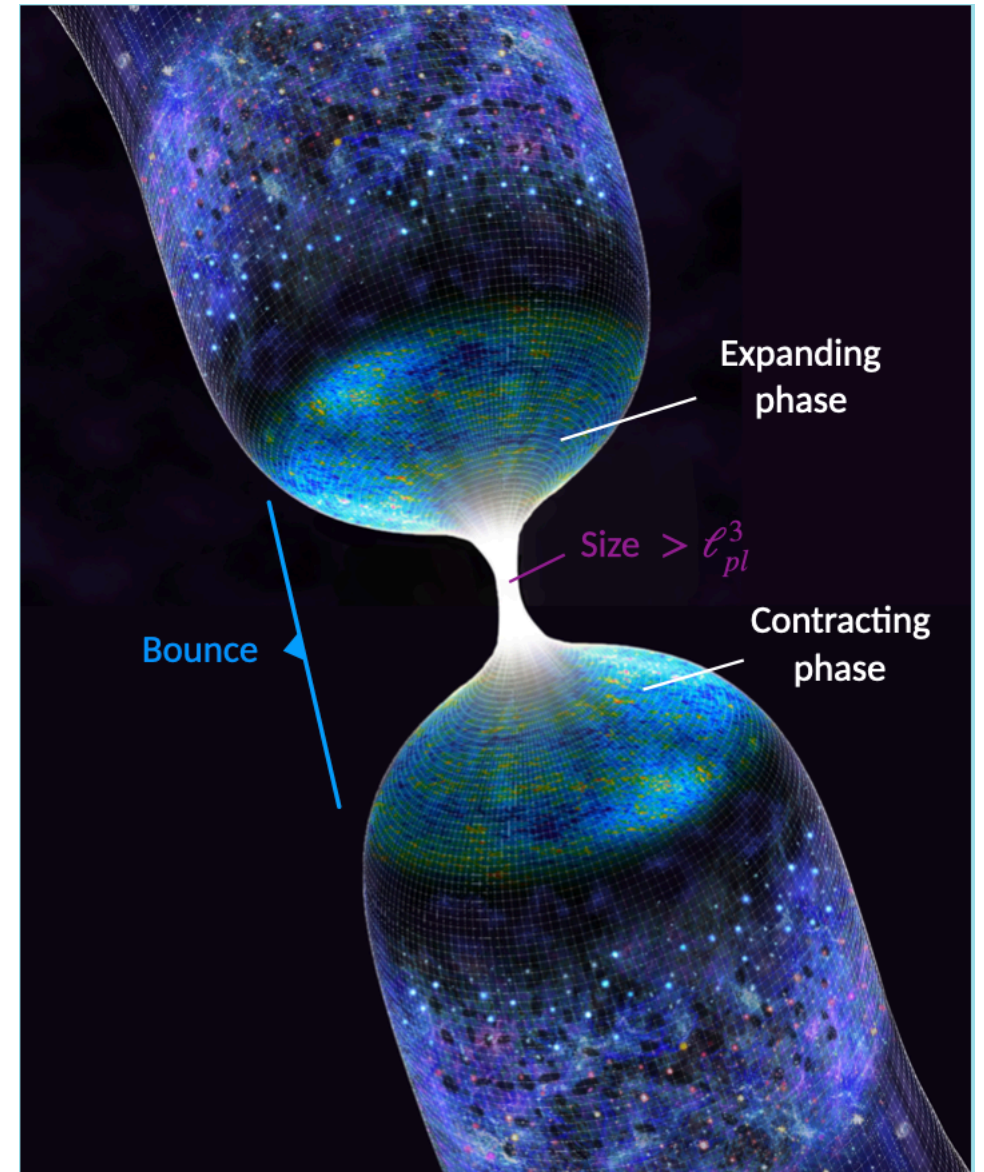
# Why bounces?

- Classical, non-singular bounce:

Transition from contracting to expanding phase at finite size with energy density  $\rho_B < M_{\text{pl}}^2$

$$\rightarrow a(t_B) > 0 \quad \text{and} \quad H(t_B) = \frac{\dot{a}(t_B)}{a(t_B)} = 0$$

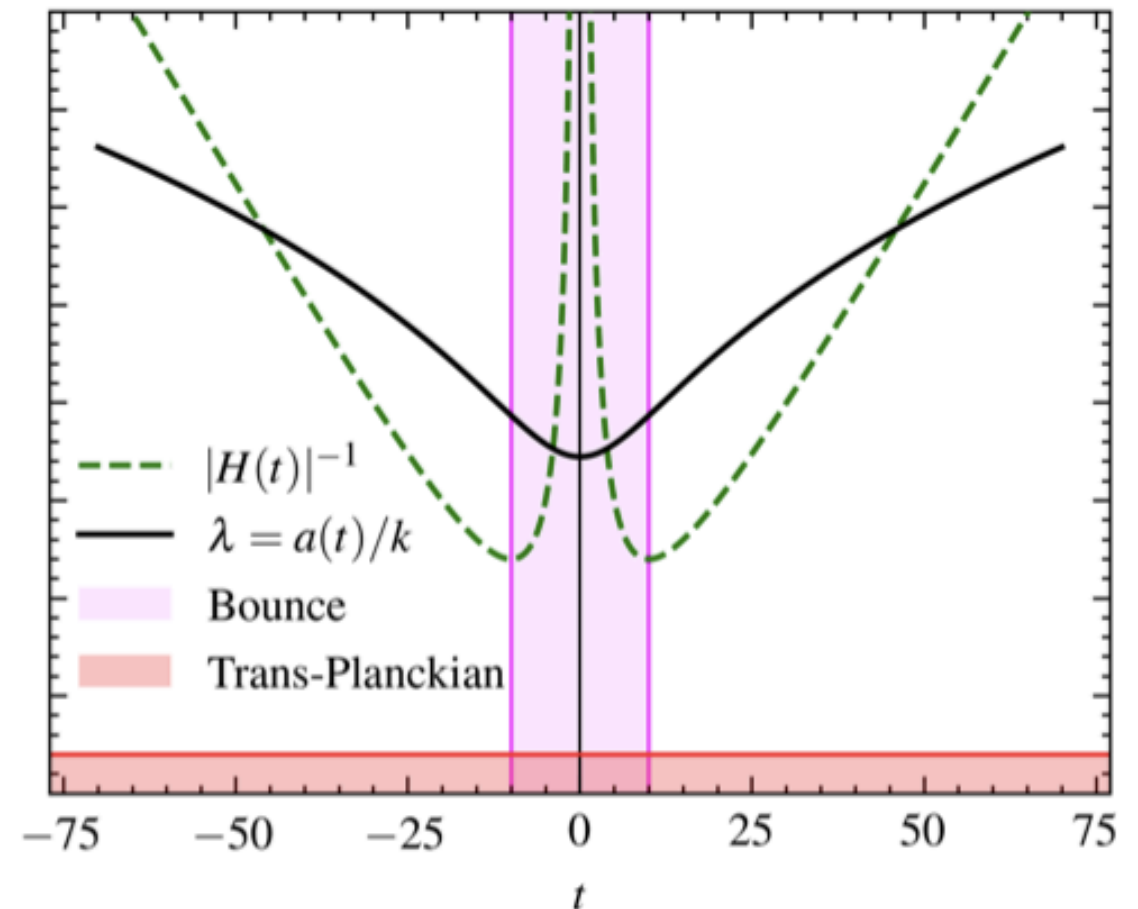
=> **initial singularity** avoided



# Why bounces?

- Mechanism to seed primordial fluctuations
- Mode wavelength above Planck length
- Mode becomes superhorizon and reenters horizon later

=> **classical** description below Planck scale



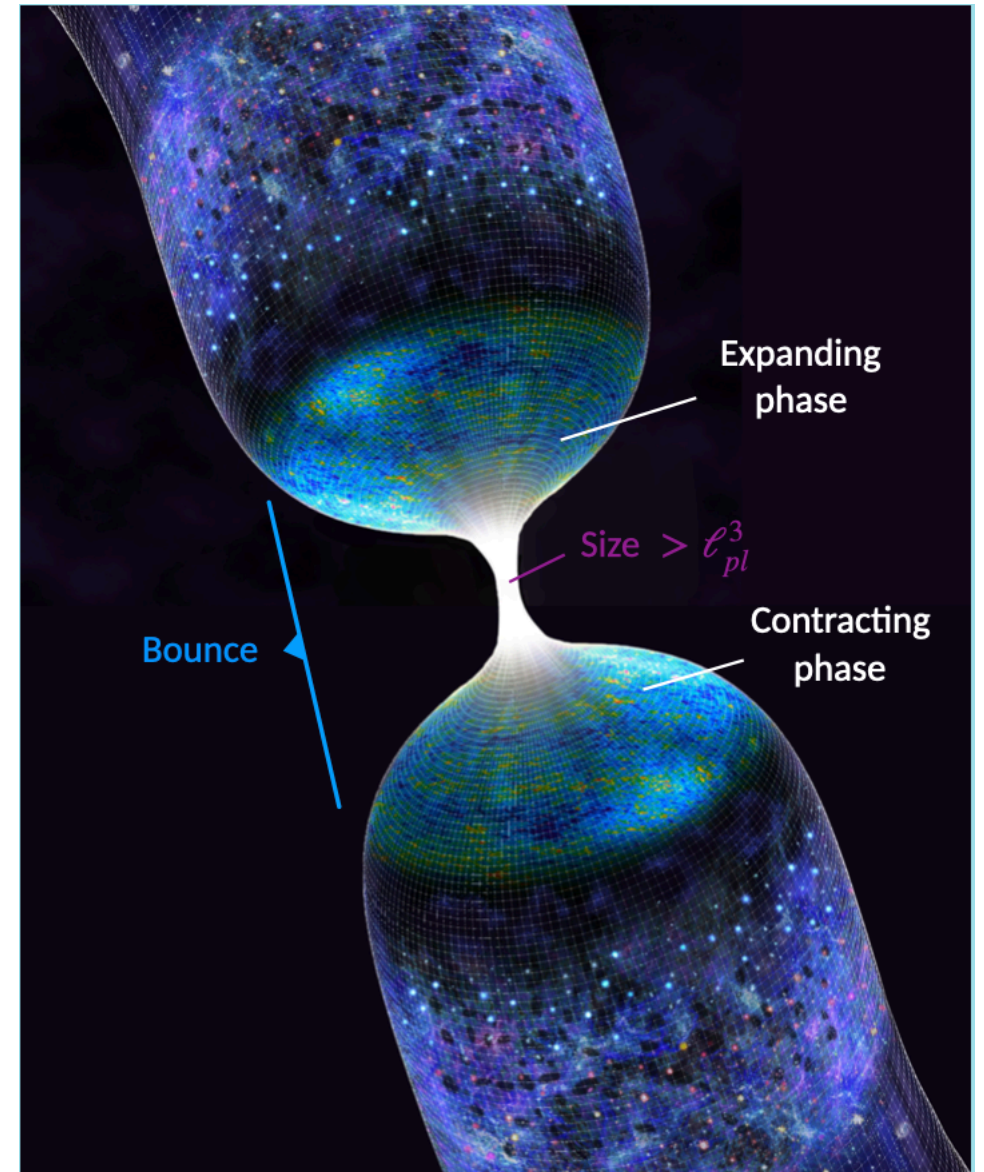
# How to bounce

- Classical, non-singular bounce:

Transition from contracting to expanding phase at finite size with energy density  $\rho_B < M_{\text{pl}}^2$

$$\rightarrow a(t_B) > 0 \quad \text{and} \quad H(t_B) = \frac{\dot{a}(t_B)}{a(t_B)} = 0$$

$\rightarrow \dot{H} > 0$  during the bounce to change from contraction to expansion



# How to bounce

- Consider universe with:

(i) Flat FRW metric:

$$ds^2 = - dt^2 + a(t)^2 d\vec{x}^2$$

(ii) Perfect fluid:

$$T_{\mu\nu} = (\rho + p)u_\mu u_\nu - pg_{\mu\nu}$$

(iii) Continuity equation:

$$\dot{\rho} = -3H(\rho + p)$$

(iv) **Null energy condition (NEC):**

En.-mom.-tensor obeys  $T_{\mu\nu}n^\mu n^\nu \geq 0$   $\forall n^\mu$  light-like

=>  $(\rho + p) \geq 0$  for a specifically chosen  $n^\mu$

# How to bounce

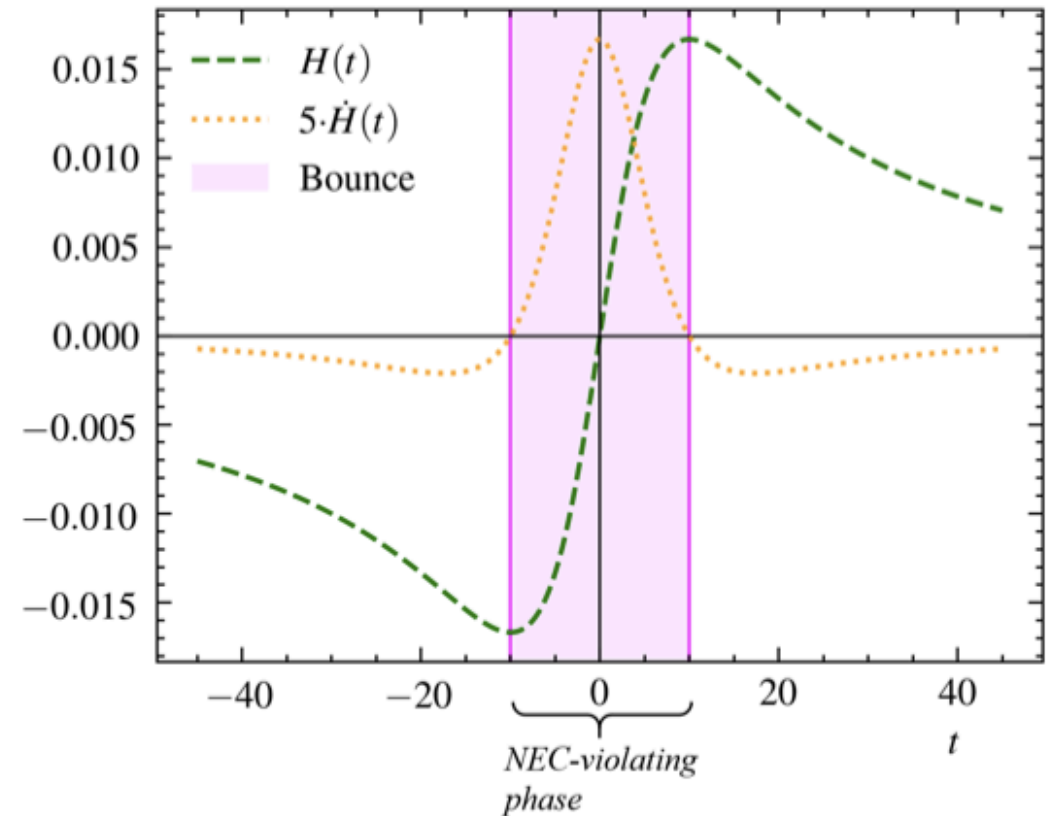
- Consider universe with GR:

$$\rightarrow \dot{H} = -\frac{1}{2M_{\text{pl}}^2} \underbrace{(\rho + p)}_{\geq 0 \text{ (NEC)}} < 0$$

- BUT: bouncing phase requires  $\dot{H} > 0$

=> **no NEC-preserving bounce possible** due to BG EOM of GR!

-> **modify gravity** to allow for bouncing phase with  $\dot{H} > 0$



# How to bounce

- Theoretical consistency: modified gravity theory with new DOF  $\pi$  must be **stable** under small perturbations

$$\mathcal{L}_{\delta\pi}^{(2)} = q_\pi \left( \dot{\delta\pi}^2 - \frac{c_\pi^2}{a^2} (\partial_i \delta\pi)^2 \right) - \frac{1}{2} m_\pi^2 \delta\pi^2 \quad \text{with} \quad \pi = \bar{\pi} + \delta\pi$$

Ghost instability:  $q_\pi < 0$  

**Stability:**

$$q_\pi > 0, c_\pi^2 \geq 0$$

Laplacian/gradient instability:  $c_\pi^2 < 0$

$$\text{Dispersion: } \omega_\pi^2 = c_\pi^2 \frac{k^2}{a^2} + m_\pi^2 \simeq c_\pi^2 \frac{k^2}{a^2} \quad (\text{small scales } k \gg m)$$

-> Exp. growing modes:  $\delta\pi_k \sim e^{i\omega_\pi t} \sim e^{\pm c_\pi |k|/a}$

# How to bounce: Horndeski?

- Pick your favourite modified gravity theory and try to bounce

G.W. Horndeski, 1974

- Scalar-tensor **Horndeski** theory (with  $X \equiv -(\nabla\phi)^2/2$ )  $\rightarrow$  maintains second-order EOM:

$$\mathcal{L}_2 = G_2(\phi, X)$$

$$\mathcal{L}_3 = -G_3(\phi, X)\square\phi$$

$$\mathcal{L}_4 = G_4(\phi, X)R + G_{4,X}[(\square\phi)^2 - (\nabla_\mu\nabla_\nu\phi)^2]$$

$$\mathcal{L}_5 = G_5(\phi, X)G^{\mu\nu}\nabla_\mu\nabla_\nu\phi - \frac{1}{6}G_{5,X}[(\square\phi)^3 - 3\square\phi(\nabla_\mu\nabla_\nu\phi)^2 + 2(\nabla_\mu\nabla_\nu\phi)^3]$$

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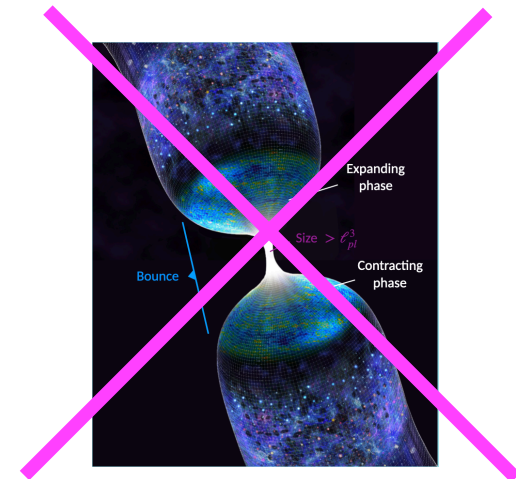
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**NO-GO**



- SVT decomposition for perturbations -> no stable region found => **NO-GO theorem**
- Downside: result only valid in certain gauges! M. Libanov et al., 2016, and T. Kobayashi, 2016

# How to bounce: generalized Proca?

L. Heisenberg, 2014

- Vector pendant to Horndeski -> **generalized Proca theory**
- Couples massive vector (Proca) field  $A^\mu$  consistently to gravity, with

Second-order EOM  
 3 propagating vector DOF  
 $A_0$  non-dynamical

$$\mathcal{L}_2 = G_2(X, F_{\mu\nu}) \quad (\text{vector field norm: } X \equiv -A^\mu A_\mu / 2)$$

$$\mathcal{L}_3 = G_3(X) \nabla_\mu A^\mu$$

$$\mathcal{L}_4 = G_4(X)R + G_{4,X}[(\nabla_\mu A^\mu)^2 - \nabla_\mu A^\nu \nabla_\nu A^\mu]$$

$$\mathcal{L}_5 = G_5(X)G^{\mu\nu} \nabla_\mu A_\nu - \frac{1}{6}G_{5,X}[(\nabla_\mu A^\mu)^3 + 2\nabla_\rho A_\sigma \nabla^\rho A^\sigma \nabla^\sigma A^\rho - 3(\nabla_\mu A^\mu) \nabla_\rho A_\sigma \nabla^\sigma A^\rho] - g_5(X)\tilde{F}^{\alpha\mu}\tilde{F}_\mu^\beta \nabla_\alpha A_\beta$$

$$\mathcal{L}_6 = G_6(X)L^{\mu\nu\alpha\beta} \nabla_\mu A_\nu \nabla_\alpha A_\beta + \frac{1}{2}G_{6,X}\tilde{F}^{\alpha\beta}\tilde{F}^{\mu\nu} \nabla_\alpha A_\mu \nabla_\beta A_\nu$$

# How to bounce: generalized Proca?

- Consider: universe filled with matter modeled as perfect fluid ( $\sim$  Schutz-Sorkin action) and gravity modified by generalized Proca
- Stability analysis:  $g_{\mu\nu} = \bar{g}_{\mu\nu} + h_{\mu\nu}$ ,  $A_\mu = \bar{A}_\mu + \delta A_\mu$  (+ similarly for matter DOF)
- Background ansatz:  $\bar{A}_\mu = (-\bar{A}_0(t), 0, 0, 0)$ ,  $\bar{g}_{\mu\nu}$ : flat FRW metric
- EOM for the background metric:

$$G_2 - G_{2,X} \bar{A}_0^2 + 3G_{3,X} H \bar{A}_0^3 + 6G_4 H^2 - 6(2G_{4,X} + G_{4,XX} \bar{A}_0^2) H^2 \bar{A}_0^2 - G_{5,XX} H^3 \bar{A}_0^5 - 5G_{5,X} H^2 \bar{A}_0^3 = \rho_M,$$

$$G_2 + \dot{\bar{A}}_0 \bar{A}_0^2 G_{3,X} + 2G_4 (3H^2 + 2\dot{H}) - 2G_{4,X} \bar{A}_0 (3H^2 \bar{A}_0 + 2H \dot{\bar{A}}_0 + 2\dot{H} \bar{A}_0) - 4G_{4,XX} H \dot{\bar{A}}_0 \bar{A}_0^3 - G_{5,XX} H^2 \dot{\bar{A}}_0 \bar{A}_0^4 - G_{5,X} H \bar{A}_0^2 (2\dot{H} \bar{A}_0 + 2H^2 \bar{A}_0 + 3H \dot{\bar{A}}_0) = -P_M.$$

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- Stability analysis:  $g_{\mu\nu} = \bar{g}_{\mu\nu} + h_{\mu\nu}$ ,  $A_\mu = \bar{A}_\mu + \delta A_\mu$  (+ similarly for matter DOF)
- Background ansatz:  $\bar{A}_\mu = (-\bar{A}_0(t), 0, 0, 0)$ ,  $\bar{g}_{\mu\nu}$ : flat FRW metric
- EOM for the background vector field:

$$\mathcal{E}_{\bar{A}_0} = \bar{A}_0 [G_{2,X} - 3G_{3,X} H \bar{A}_0 + 6H^2 (G_{4,X} + \bar{A}_0^2 G_{4,XX}) + \bar{A}_0 H^3 (3G_{5,X} + \bar{A}_0^2 G_{5,XX})] = 0.$$

->  $\bar{A}_0$  does not carry its own dynamics, **fully determined by background evolution**:  $\bar{A}_0 = \bar{A}_0(H)$

# How to bounce: generalized Proca?

- At the level of perturbations -> do scalar-vector-tensor decomposition:

- Metric:

$$ds^2 = - (1 + 2\alpha)dt^2 + 2(V_i + \partial_i\chi)dtdx^i + a(t)^2[(1 + 2\zeta)\delta_{ij} + 2\partial_i\partial_j E + h_{ij}]dx^i dx^j$$

- Proca field:

$$A^0 = -\bar{A}_0(t) + \delta A$$

$$A^i = \frac{1}{a^2}\delta^{ij}(\partial_j\chi_V + \partial_j)$$

+ similarly for fluid quantities

Expand total action up to 2<sup>nd</sup> order in perturbations where S,V,T-modes decouple -> study them separately

# How to bounce: generalized Proca?

- **Tensor modes:** Only contribution from the metric! L. Heisenberg et al., 2018

$$S_T^{(2)} = \int dt d^3x \sum_{i=1}^2 q_T \left[ \dot{h}_i^2 - \frac{c_T^2}{a^2} (\partial h_i)^2 \right]$$

- Stability coefficients:

$$q_T \equiv 2G_4 - 2\bar{A}_0^2 G_{4,X} - \bar{A}_0^3 H G_{5,X}$$
$$c_T^2 \equiv \frac{2G_4 - \bar{A}_0^2 \dot{\bar{A}}_0 G_{5,X}}{q_T}$$

# How to bounce: generalized Proca?

- **Vector modes:** After integrating out non-dynamical and redefining DOF L. Heisenberg et al., 2018

$$S_V^{(2)} \simeq \int dt d^3x \frac{a^3}{2} q_V \left[ \dot{Z}_i^2 - \frac{c_V^2}{a^2} (\partial_j Z_i)^2 \right] \quad (\text{in the small-scale limit})$$

- Stability coefficients:

$$q_V \equiv G_{2,F} + 2\bar{A}_0^2 G_{2,Y} - 4\bar{A}_0 H g_5 + 2H^2 (G_6 + \bar{A}_0^2 G_{6,X})$$

$$c_V^2 \equiv 1 + \frac{\bar{A}_0^2 (2G_{4,X} + \bar{A}_0 H G_{5,X}^2)}{2q_T q_V} + \frac{2[\dot{H} G_6 - \bar{A}_0^2 G_{2,Y} - (\bar{A}_0 H - \dot{\bar{A}}_0)(\bar{A}_0 H G_{6,X} - g_5)]}{q_V}$$

# How to bounce: generalized Proca?

- **Scalar modes:**  $S_S^{(2)} = \int dt d^3x (\mathcal{L}^{\text{flat}} + \mathcal{L}_\zeta + \mathcal{L}_E)$  L. Heisenberg et al., 2018

$w_i$ : collections of  $G_i$

$$\begin{aligned} \mathcal{L}^{\text{flat}} = a^3 & \left[ \left( \frac{w_2}{\bar{A}_0} (\partial_i \alpha) - w_1 (\partial_i \delta A) \right) \frac{\partial^i \chi}{a^2} - w_3 \frac{(\partial \alpha)^2}{a^2} + w_4 \alpha^2 + w_3 \frac{(\partial_i \delta A) (\partial^i \alpha)}{a^2 \bar{A}_0} + w_3 \left( \partial_i \alpha - \frac{1}{2 \bar{A}_0} (\partial_i \delta A) \right) \frac{\partial_i \dot{\psi}}{a^2 \bar{A}_0} \right. \\ & + w_8 \frac{\delta A \alpha}{\bar{A}_0} + \left( w_6 (\partial_i \alpha) + \frac{w_2 - \bar{A}_0 w_6}{2 \bar{A}_0^2} (\partial_i \delta A) \right) \frac{\partial^i \psi}{a^2} - w_3 \frac{(\partial \delta A)^2}{4 a^2 \bar{A}_0^2} + w_5 \frac{\delta A^2}{\bar{A}_0^2} - w_3 \frac{(\partial \dot{\psi})^2}{4 a^2 \bar{A}_0^2} + w_7 \frac{(\partial \psi)^2}{2 a^2} - \alpha \delta \rho_M \\ & \left. - (\rho_M + P_M) \frac{(\partial_i v) (\partial^i \chi)}{a^2} - v \delta \dot{\rho}_M - 3H(1 + c_M^2) v \delta \rho_M - \frac{1}{2} (\rho_M + P_M) \frac{(\partial v)^2}{a^2} - \frac{c_M^2}{2(\rho_M + P_M)} \delta \rho_M^2 \right], \quad (42) \end{aligned}$$

$$\begin{aligned} \mathcal{L}_\zeta = a^3 & \left[ 3 \left( \frac{w_2}{\bar{A}_0} \delta A - w_1 \alpha - (\rho_M + P_M) v \right) \dot{\zeta} - \frac{2}{a^2} [q_T (\partial_i \chi) + \alpha_3 (\partial_i \psi)] \partial^i \dot{\zeta} - 3q_T \dot{\zeta}^2 \right. \\ & \left. + [2(q_T - 2\bar{A}_0 \alpha_3) \partial_i \alpha + 2\alpha_3 (\partial_i \delta A)] \frac{\partial^i \zeta}{a^2} + \mathcal{F}_T \frac{(\partial \zeta)^2}{a^2} \right], \quad (43) \end{aligned}$$

$$\begin{aligned} \mathcal{L}_E = a^3 & \left[ -2q_T (\partial_i \ddot{\zeta}) - 2B_2 (\partial_i \dot{\zeta}) - w_1 (\partial_i \dot{\alpha}) - (\dot{w}_1 + 3Hw_1) \partial_i \alpha + \frac{w_2}{\bar{A}_0} (\partial_i \dot{\delta A}) - B_5 (\partial_i \delta A) \right. \\ & \left. - (\rho_M + P_M) [\partial_i \dot{v} - 3Hc_M^2 (\partial_i v)] \right] \partial^i E. \quad (44) \end{aligned}$$

# How to bounce: generalized Proca?

- **Scalar modes:** After redefining and integrating out non-dynamical DOF

$$S_S^{(2)} \simeq \int dt d^3x a^3 \left[ q_S \left( \dot{\mathcal{R}}_k^2 - c_S^2 \frac{k^2}{a^2} \mathcal{R}_k^2 \right) + q_M \left( \dot{\delta\tilde{\rho}}_k^2 - c_M^2 \frac{k^2}{a^2} \delta\tilde{\rho}_k^2 \right) \right]$$

- Stability coefficients:

$$q_S \equiv \frac{q_T(3w_2^2 + 4q_T w_5)}{(w_1 - 2w_2)^2}, \quad q_M \equiv \frac{a^2}{2(\rho + p)} \quad + \quad c_S^2 \quad \text{and} \quad c_M^2$$

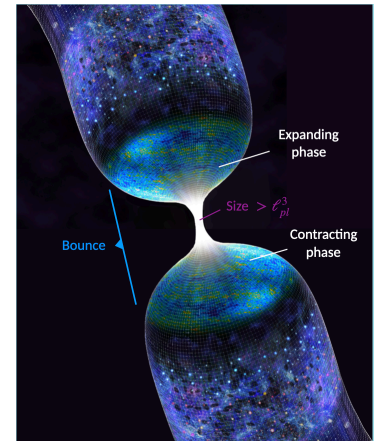
# How to bounce: generalized Proca?

- **Stability analysis:** stable bounce requires over full cosmological time evolution ( $-\infty < t < +\infty$ )

$$q_T > 0, \quad c_T^2 \geq 0, \quad q_V > 0, \quad c_V^2 \geq 0, \quad q_S > 0, \quad c_S^2 \geq 0, \quad q_M > 0, \quad c_M^2 \geq 0$$

-> gives constraints on coupling functions  $G_i$  and their derivatives

- Additional constraint for bouncing phase:  $\dot{H} > 0$  (during some finite time interval)

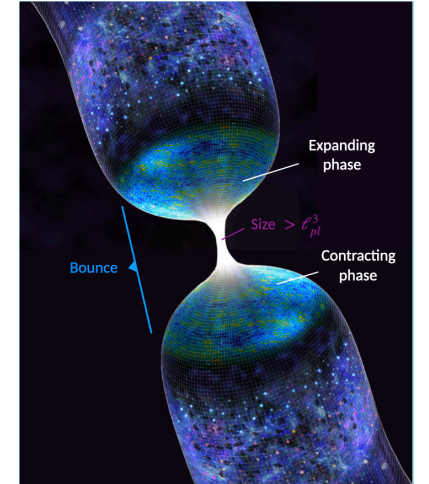


# How to bounce: generalized Proca?

- Stability in the matter sector:

$$\text{require } q_M = \frac{a^2}{2(\rho + p)} > 0 \quad \rightarrow \quad \rho + p \geq 0$$

- Combining background EOM:  $\rho + p = - \left( 2q_T + \frac{3w_2^2}{2w_5} \right) \dot{H}$



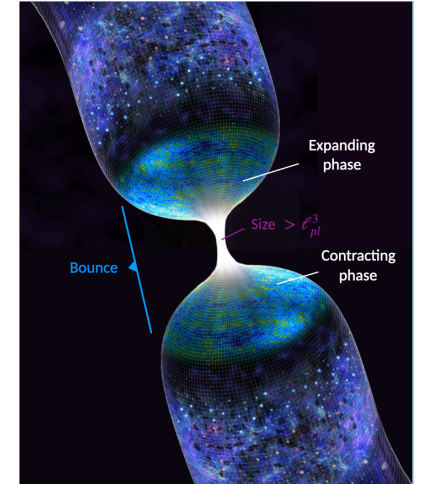
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$$(i) \quad \rho + p > 0 : \quad \text{At the bounce } \dot{H}(t_B) > 0 \quad \rightarrow \quad 0 < 2q_T(t_B) < - \frac{3w_2(t_B)^2}{2w_5(t_B)} \quad \text{but } w_2(t_B) = 0$$



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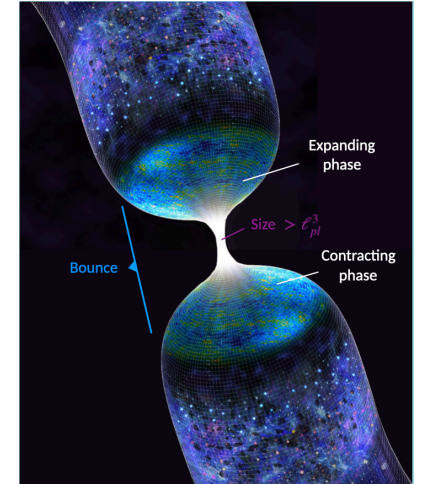
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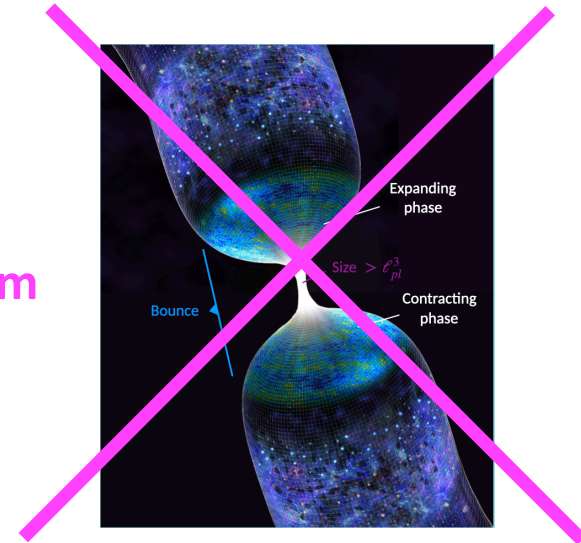
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(ii)  $\rho + p = 0$  : scalar kinetic coefficient vanishes  $q_S = 3w_2^2 + 4w_5q_T = 0$

=> either encounter **instabilities** in the **tensor** or **scalar** sector, **no stable bounce** possible!

NO-GO theorem



# Conclusion

- non-singular cosmological bounces provide an alternative to inflation that do not suffer from problems afflicting inflation (e.g. singularity and trans-Planckian problem)
- bounces not possible in pure GR -> modified gravity theories provide a way out
- scalar-tensor theories: Horndeski cannot bounce (gauge-dependent)
- **No-Go theorem for bounces mediated by generalized Proca fields:** Either run into instabilities in the matter, tensor or scalar sector already at the linear level of perturbations!
- No-go theorem gauge-independent -> theoretically robust