



CERN, from a beam instrumentation perspective

A deeper view on some traditional instruments

D. Alves on behalf of the CERN SY-BI-IQ section

Material providers



Acknowledgements

- R. Jones (CERN)
- T. Lefèvre (CERN)
- M. Gasior (CERN)
- O. Marqversen (CERN)
- S. Thoulet (CERN)
- R. Ruffieux (CERN)
- R. Hernandez (IFIC)
- P. Forck (GSI)
- R. Steinhagen (GSI)
- M. Krupa (CERN)

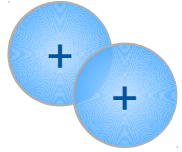
CERN SY-BI-IQ section

Outline

- CERN & Beam instrumentation
- Instruments in SY-BI-IQ
 - Fast beam current transformers
 - Beam position monitors
 - Tune monitors
 - *Potpourri* of other instruments

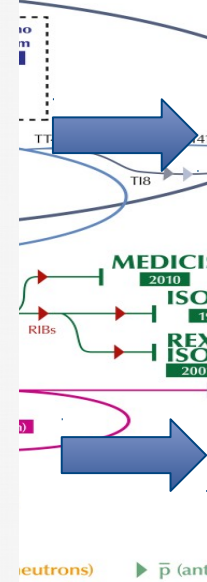
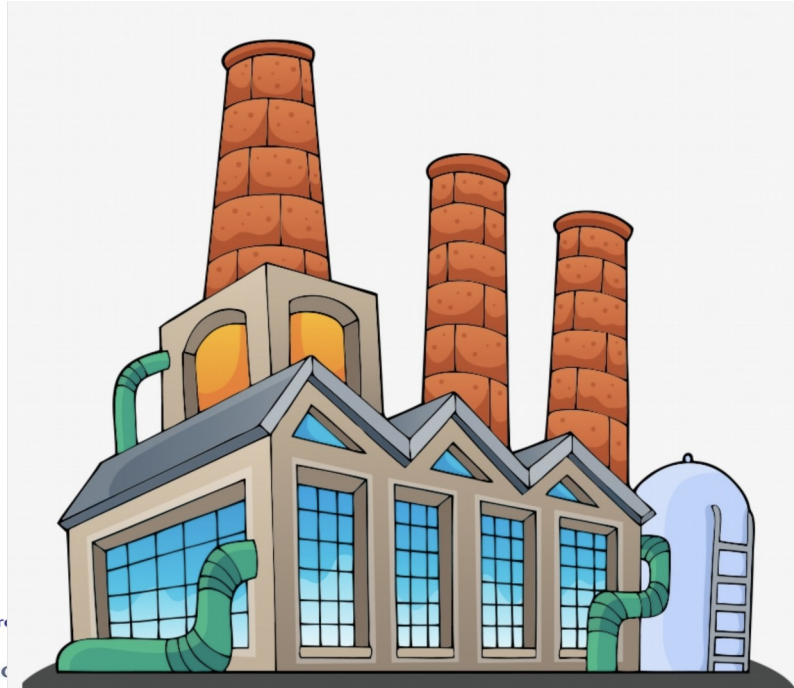
CERN

The CERN accelerator complex *Complexe des accélérateurs du CERN*

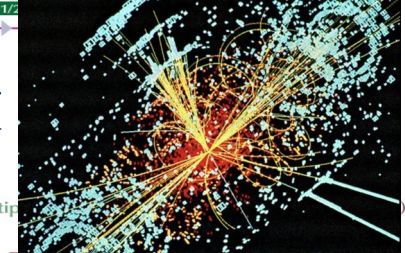


► H^- (hydrogen)

LHC



East Area



Electron Accelerator for Research // **AWAKE** - Advanced **W**AKEfield Experiment // **ISOLDE** - Isotope Separator OnLine // **REX/HIE-ISOLDE** - Radioactive Experiment/High Intensity and Energy **ISOLDE** // **MEDICIS** // **LEIR** - Low Energy Ion Ring // **LINAC** - LINear ACcelerator // **n_TOF** - Neutrons Time Of Flight // **HiRadMat** - High-Radiation to Materials // Neutrino Platform



Beam instrumentation



- What do we mean by beam instrumentation?
 - The “eyes” of the machine operators
 - The instruments that observe beam behaviour
 - Enable beam optimization (steering, stability, lifetime, luminosity, ...)
- What does work in beam instrumentation entail?
 - Design, construction & operation of instruments to observe particle beams
 - R&D to find new or improve existing techniques to fulfill new requirements

Colliding beams luminosity

$$\mathcal{L} = \frac{N_1 N_2 f N_b}{2\pi \sqrt{\sigma_{1x}^2 + \sigma_{2x}^2} \sqrt{\sigma_{1y}^2 + \sigma_{2y}^2}}$$

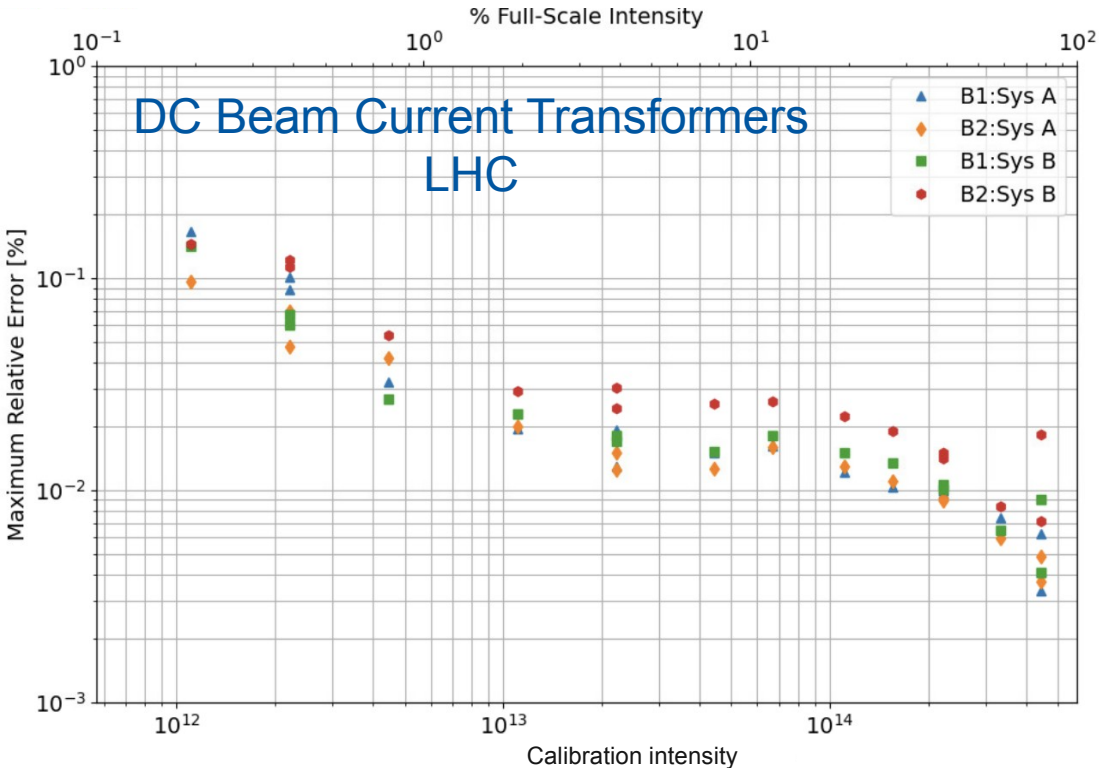
Goal is to maximise $\int \mathcal{L}(t) dt$!!!

LHC: $N_{1,2} \sim 10^{11}$, $f \sim 11 \text{ kHz}$, $N_b \sim 1600$, $\sigma \sim 10 \mu\text{m} \Rightarrow \mathcal{L} \sim 10^{34} \text{ cm}^{-2} \text{ s}^{-1}$
 Collisions: $6 \times 10^8 \text{ s}^{-1} \sim 20$ per bunch crossing

- Minimise beam losses (i.e. keep as large as possible)
- Maximise beam sizes
- Minimise beam sizes
- Minimise beam separation
- Minimise transverse beam sizes
- Luminosity can also be measured directly
- Luminosity can also be measured directly

Beam instrumentation

Beam intensity measurement

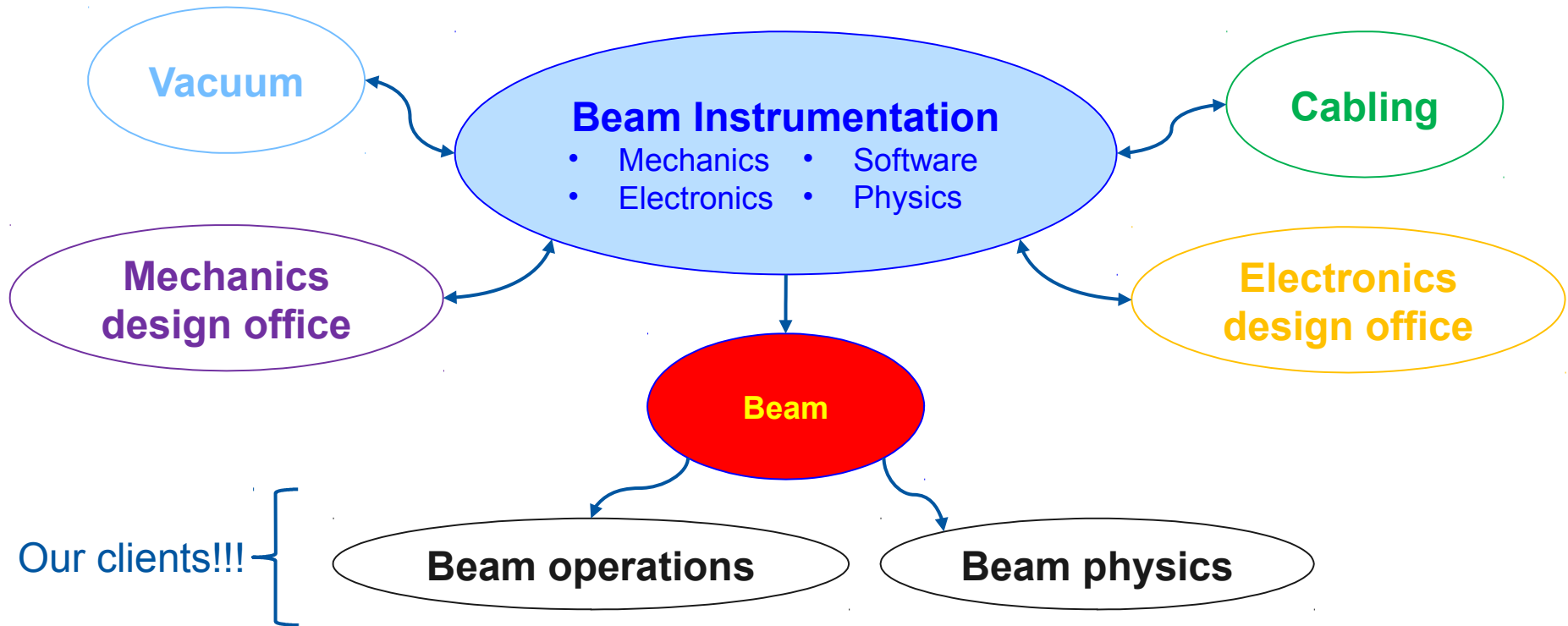


- Need to cover ~ 5 orders of magnitude
- $> 1\%$ of full-scale, relative error $< 0.03\%$

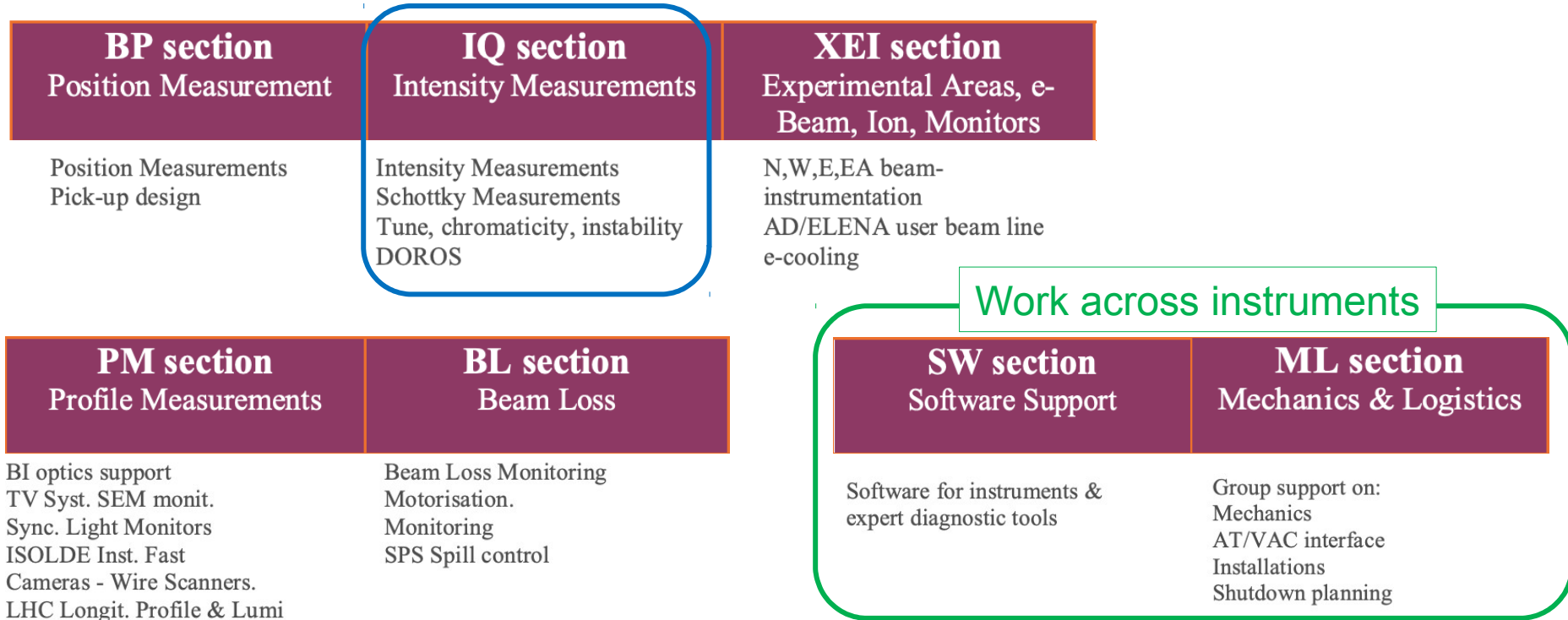
Beam instrumentation – who are we?

- Technicians, Engineers, Physicists
 - Mechanics
 - Electronics (analog + digital)
 - Software
 - Instrumentation physics
 - Beam physics

Beam instrumentation – where are we?



Beam instrumentation group structure at CERN

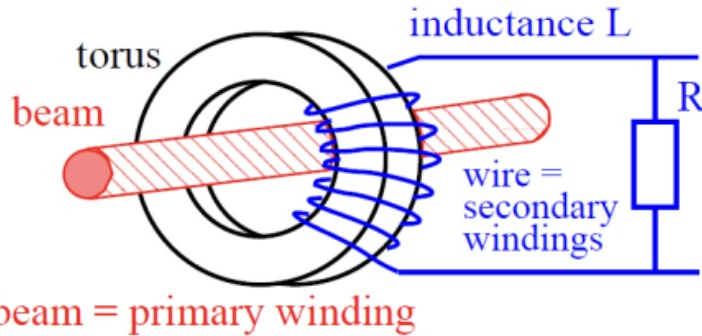
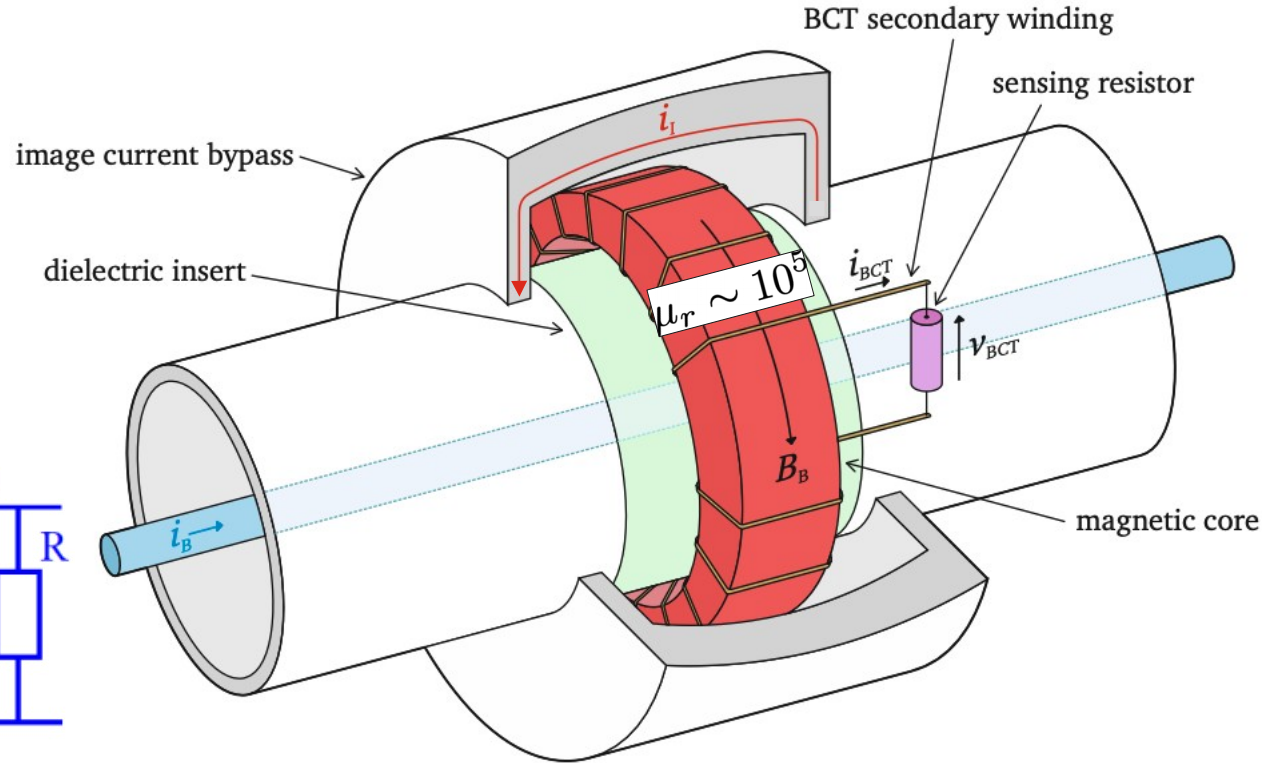


(Some) instruments in the IQ section

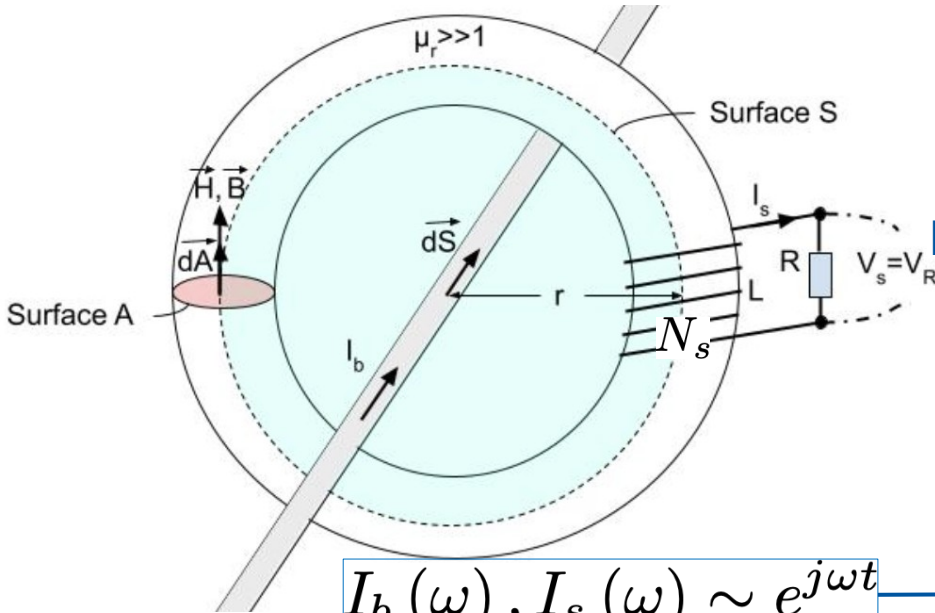
Instrument	Where?	What do we measure?
Fast Beam Current Transformers	<ul style="list-style-type: none">All transfer linesMost circular machines	Beam intensity, bunch intensity
DC Beam Current Transformers	<ul style="list-style-type: none">Most circular machines	Beam intensity
Tune measurement systems	<ul style="list-style-type: none">All circular machines	Tune (resonant beam oscillations)
Beam position monitoring	<ul style="list-style-type: none">AD, ELENA and LEIRSPS and LHC (DOROS)	Beam position
Schottky monitors	<ul style="list-style-type: none">ELENA, LEIR and LHC	Momentum distribution, synchrotron tune, betatron tune, chromaticity, ...
Head-tail + Instability monitoring	<ul style="list-style-type: none">SPS and LHC	Intra-bunch oscillations
LHC beam-based feedbacks	<ul style="list-style-type: none">LHC	Orbit feedback, tune feedback

Fast Beam Current Transformers

Fast Beam Current Transformers



Fast Beam Current Transformers



Ampere's law:
$$\int_S (\vec{\nabla} \times \vec{H}) \cdot d\vec{S} = I_b + N_s I_s$$

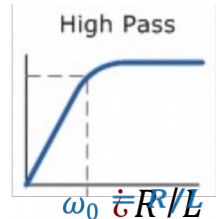
$$B = \mu_0 \mu_r H = \frac{\mu_0 \mu_r}{2\pi r} (I_b + N_s I_s)$$

Faraday's law:
$$V_s = -N_s \frac{\partial \phi_B}{\partial t} = -N_s \frac{\partial}{\partial t} \int \vec{B} \cdot d\vec{A}$$

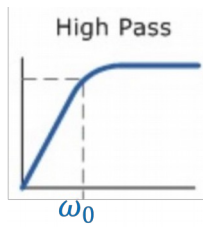
$$R I_s = \frac{\mu_0 \mu_r A N_s}{2\pi r} \frac{\partial}{\partial t} (I_b + N_s I_s)$$

$$I_b(\omega), I_s(\omega) \sim e^{j\omega t}$$

$$\frac{I_s(\omega)}{I_b(\omega)} = -\frac{1}{N_s} \frac{\frac{\omega^2 L^2}{R^2} + \frac{j\omega L}{R}}{1 + \frac{\omega^2 L^2}{R^2}}$$



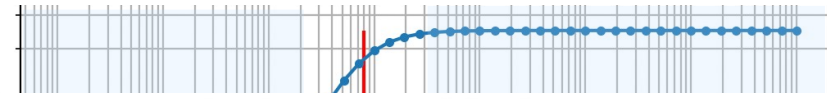
Fast Beam Current Transformers



$$\frac{I_s(\omega)}{I_b(\omega)} = -\frac{1}{N_s} \frac{\frac{\omega^2 L^2}{R^2} + \frac{j\omega L}{R}}{1 + \frac{\omega^2 L^2}{R^2}}$$

$\omega \ll R/L$

derivative



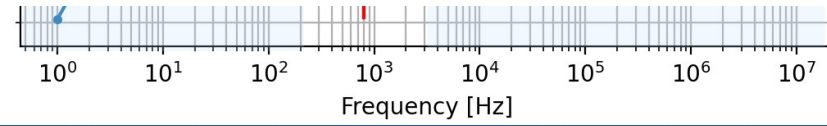
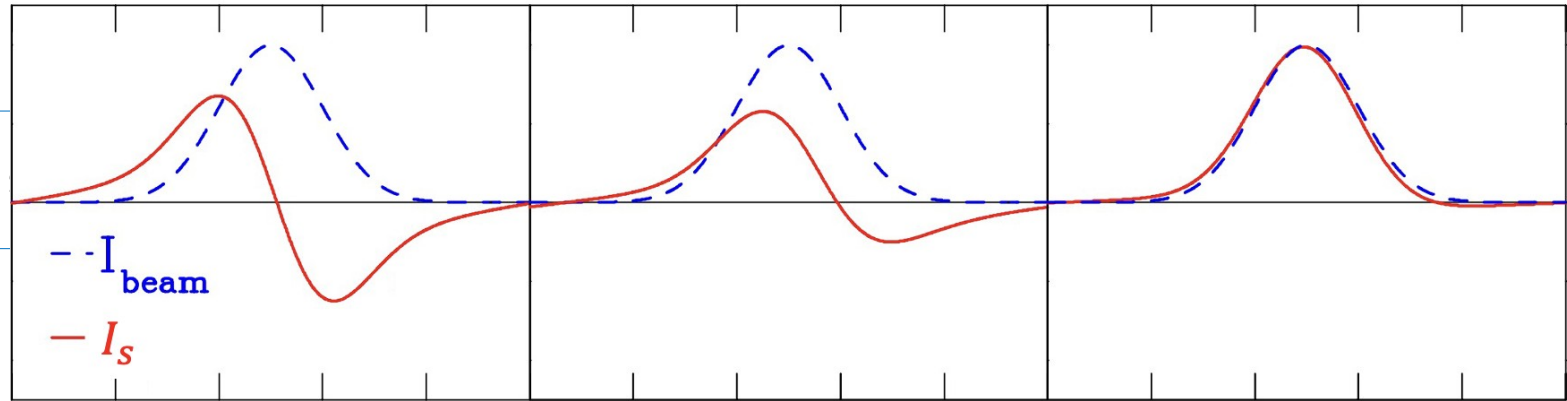
intermediate

proportional

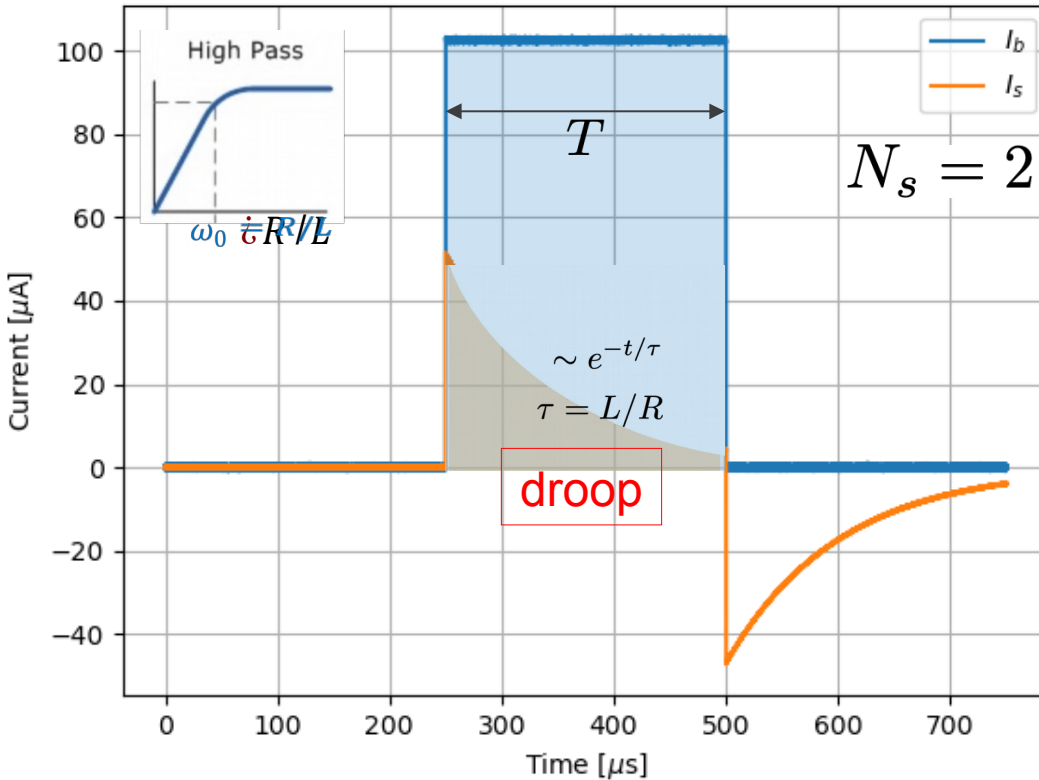
$\omega \gg R/L$

$\frac{I_s(\omega)}{I_b(\omega)}$

$\frac{1}{N_s}$



Fast Beam Current Transformers – transfer line



$$Q = \int_0^T I(t) dt$$

How to fix it? – Easy, make $\tau \gg T$

- Increase L by increasing N_s

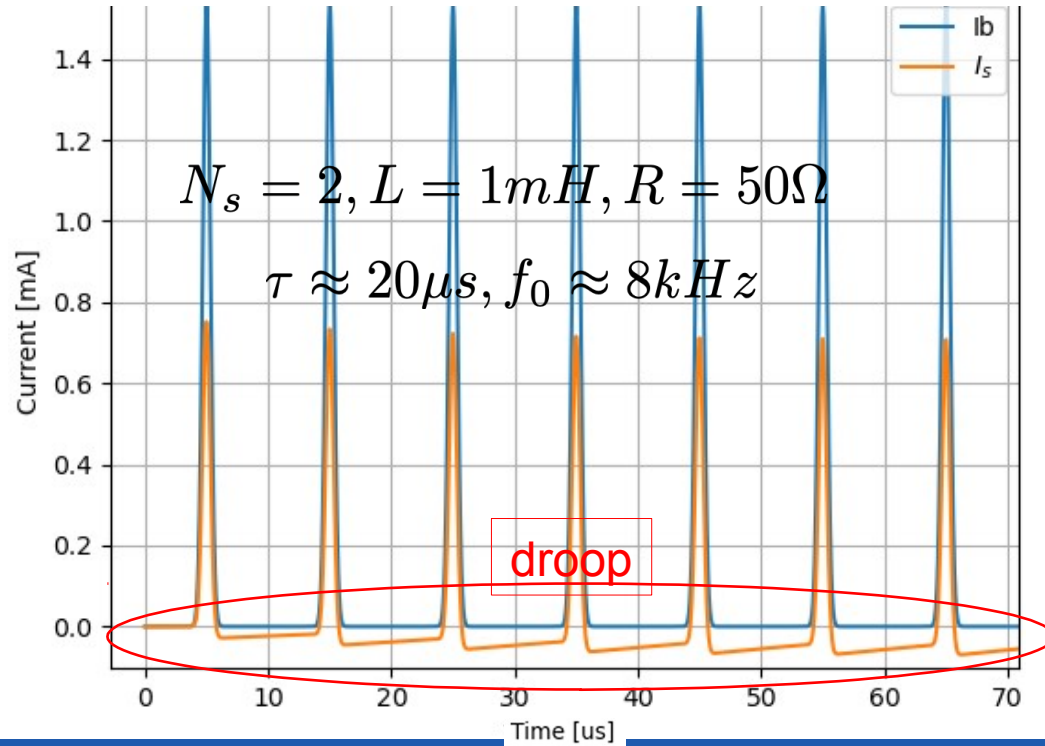
$$L = \frac{\mu_0 \mu_r A N_s^2}{2\pi r} \quad \text{BUT} \quad V_s \propto -\frac{R}{N_s} I_b$$

- Decrease R

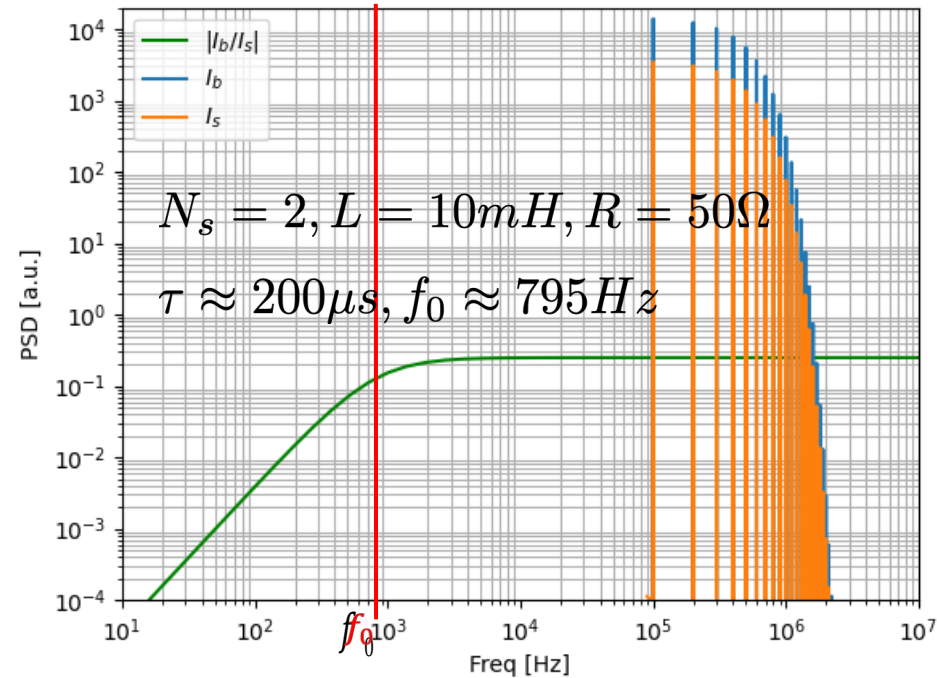
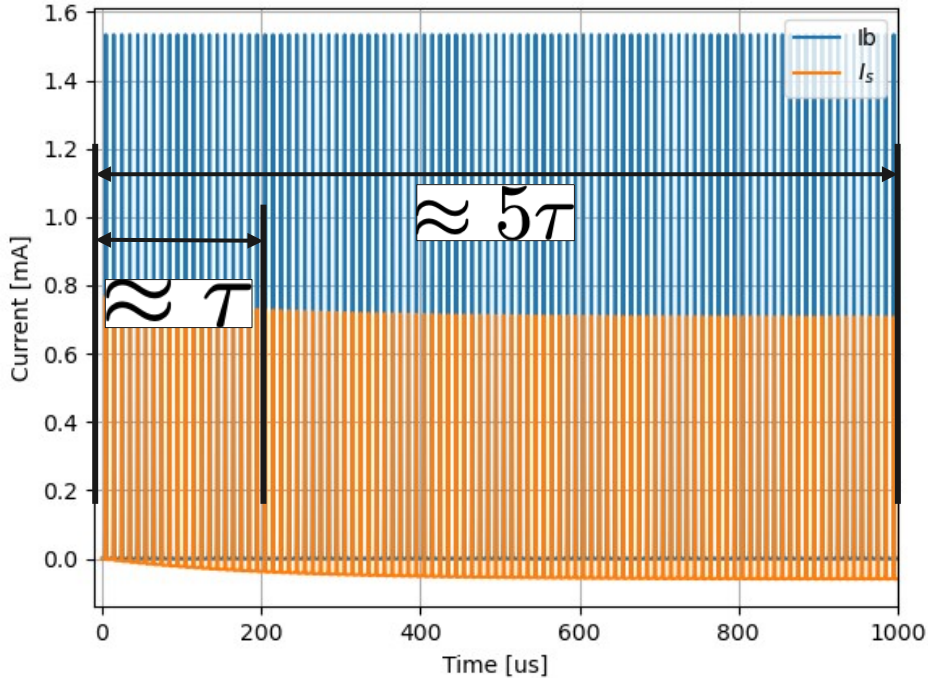
Again, the price to pay is $V_s \propto -\frac{R}{N_s} I_b$

Fast Beam Current Transformers – circular machine

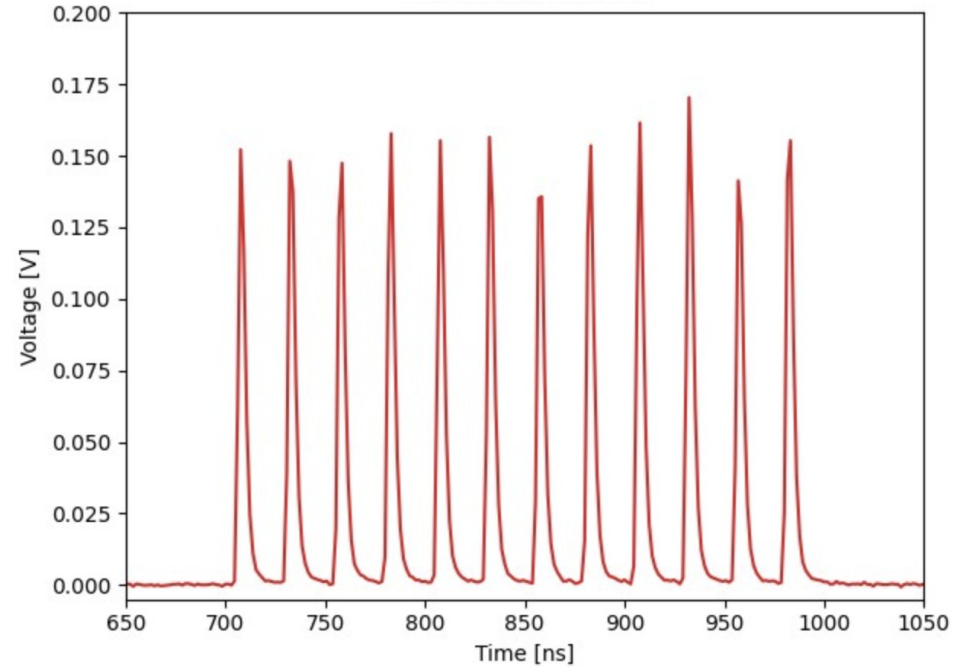
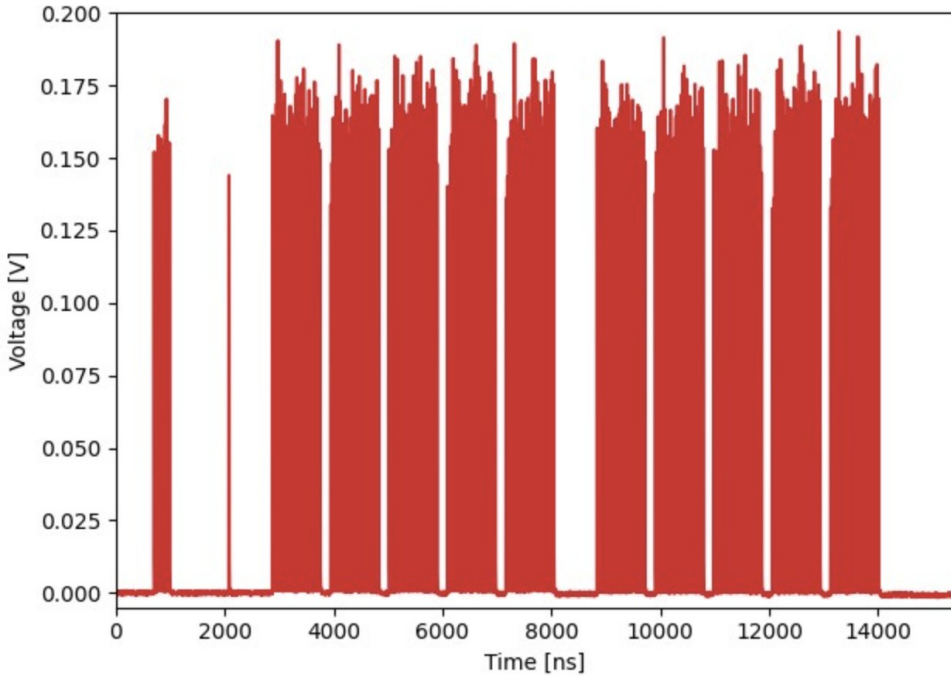
1 bunch with $f_{rev} = 100kHz$



Fast Beam Current Transformers – circular machine

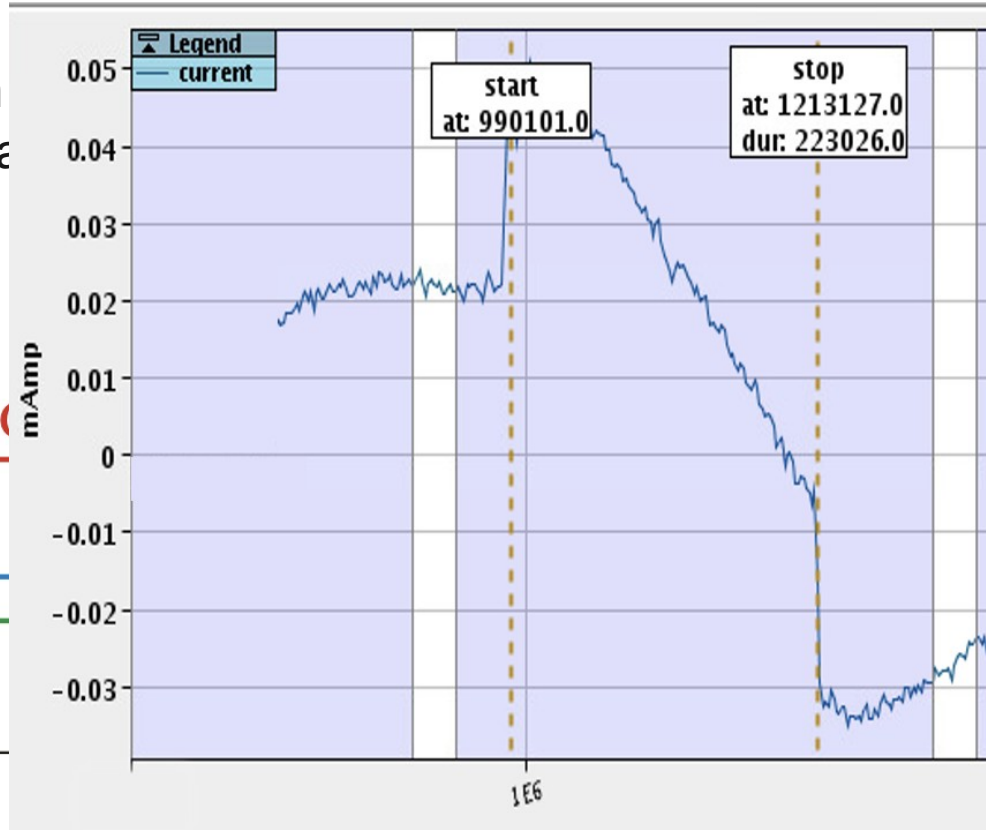
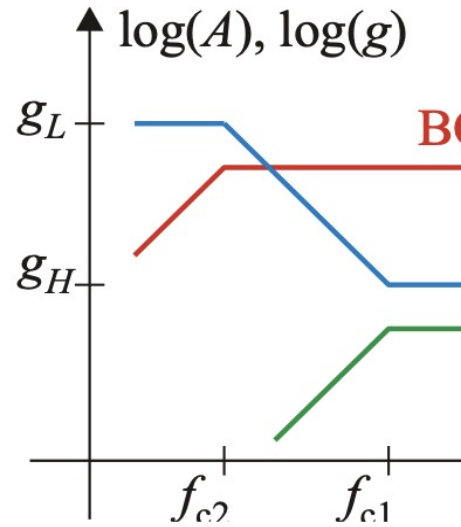


Fast Beam Current Transformers – live measurements

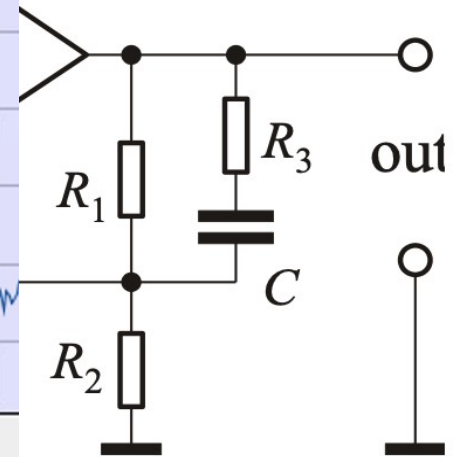


Fast Beam Current Transformers – droop mitigation

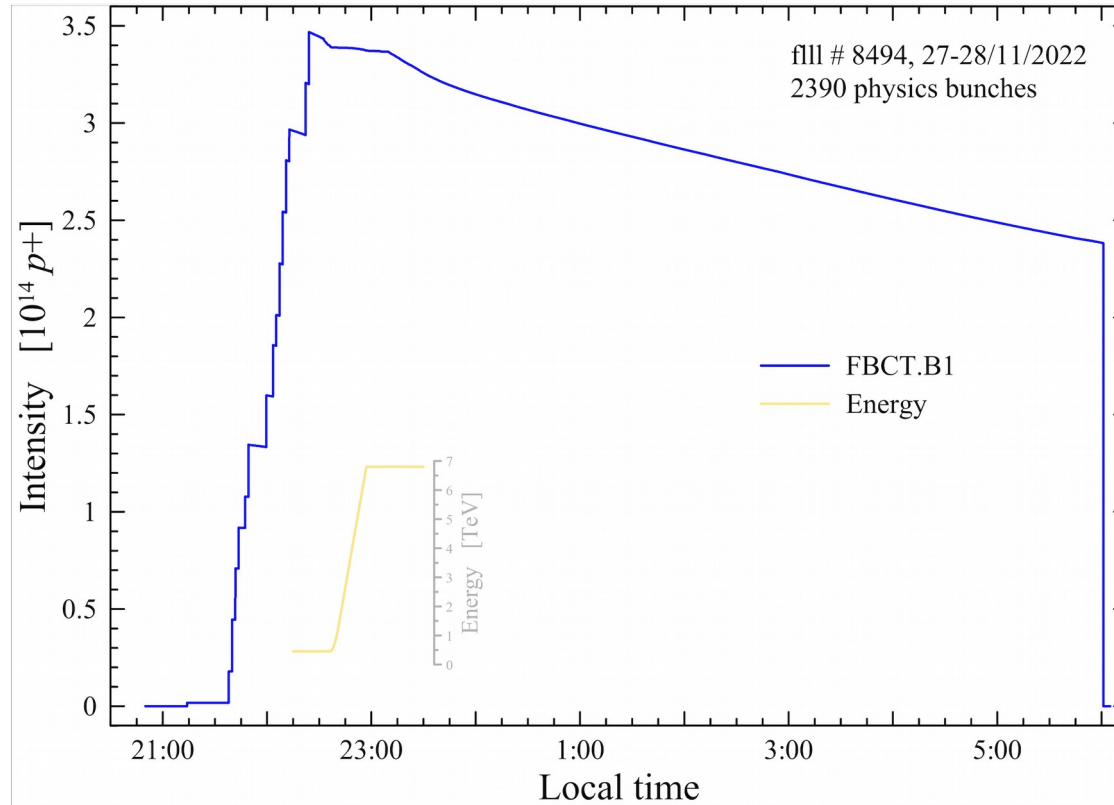
- Compensation
- General accuracy



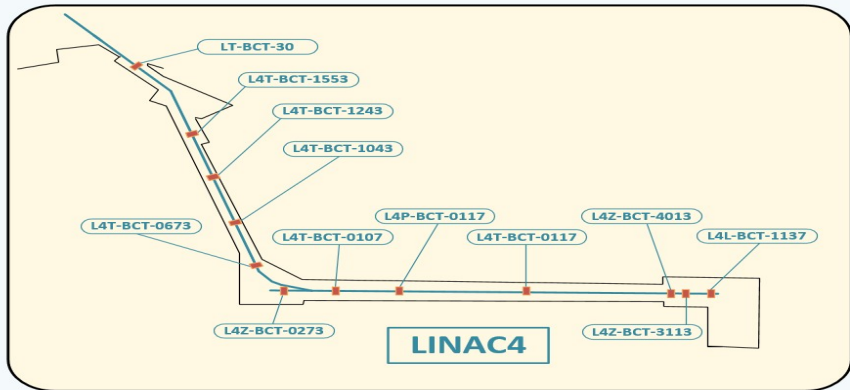
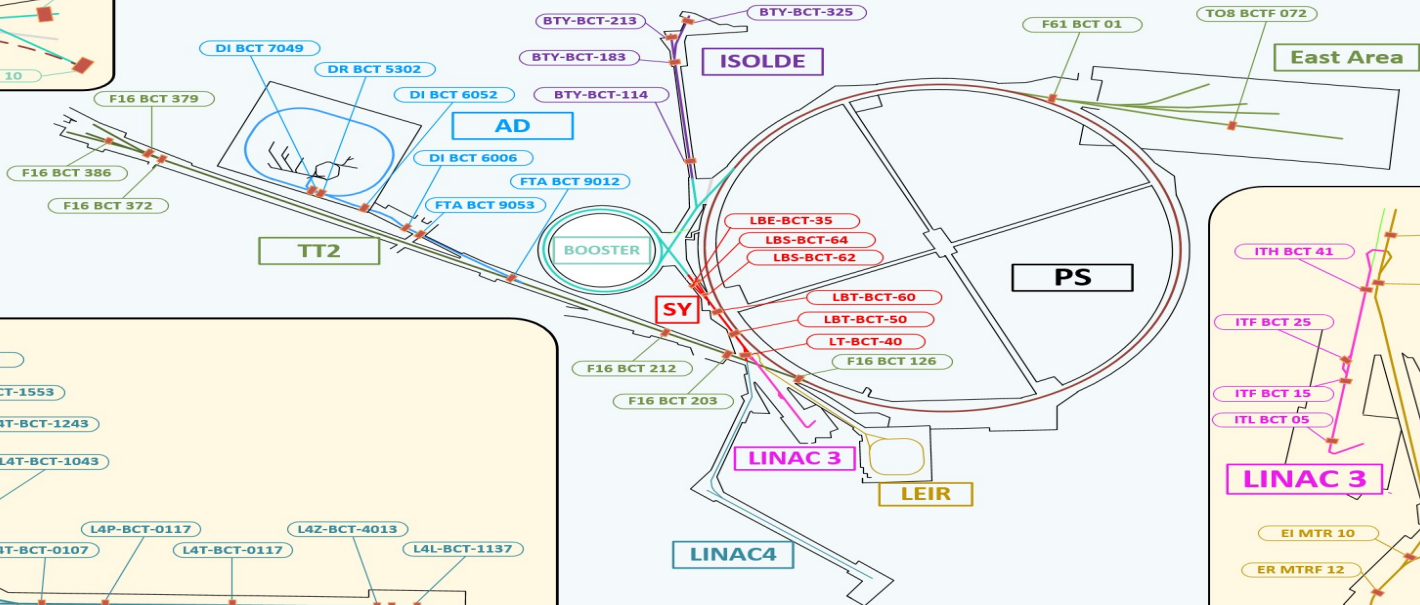
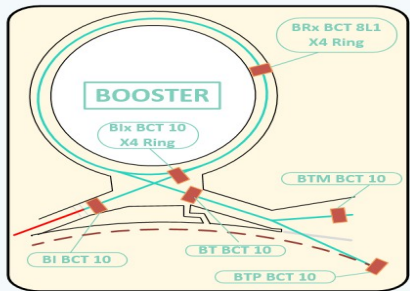
roop time)



Fast Beam Current Transformers – live measurements



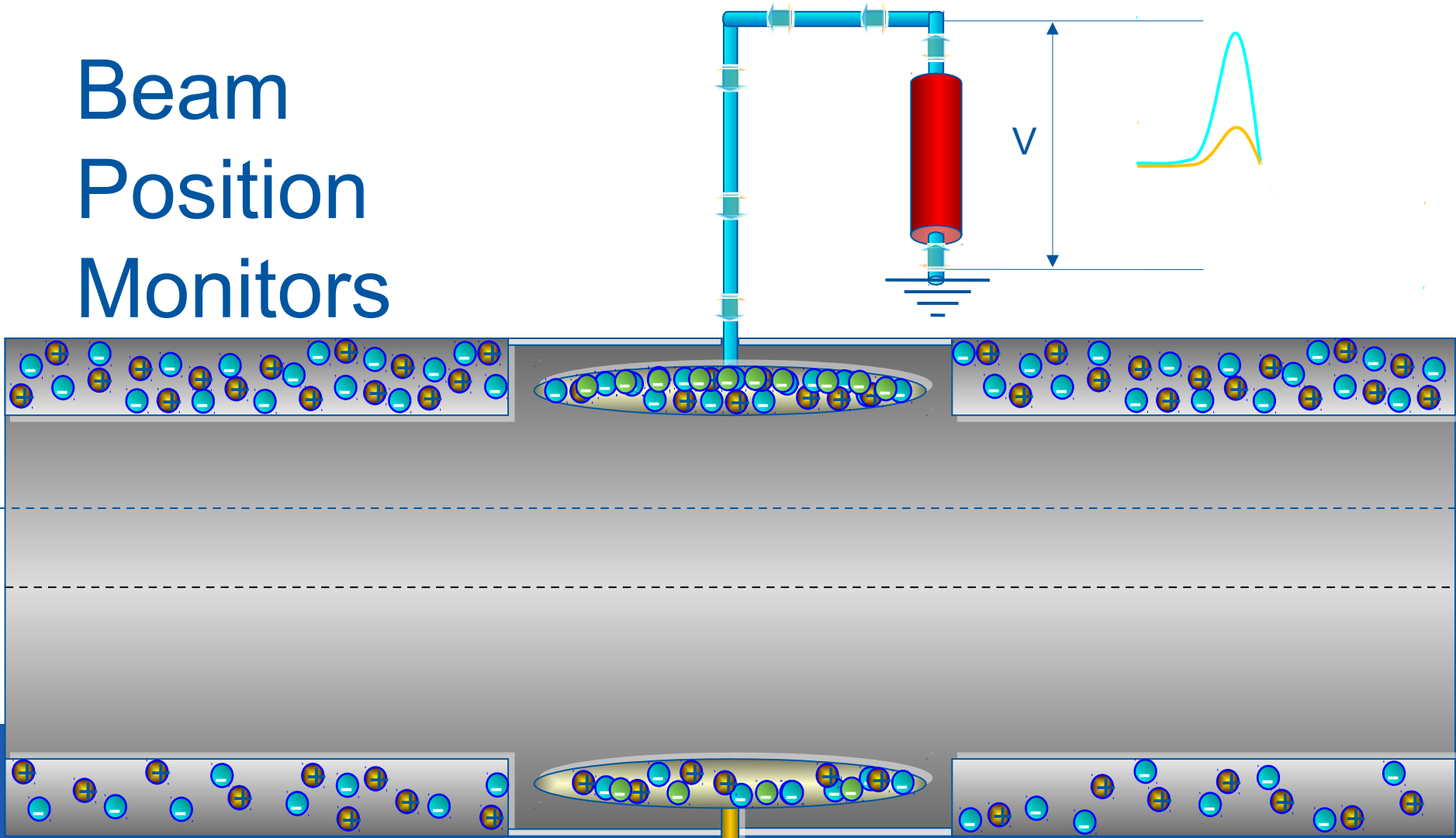
Fast BCT PS Complex



~ 70 installations

Beam Position Monitors

Beam Position Monitors



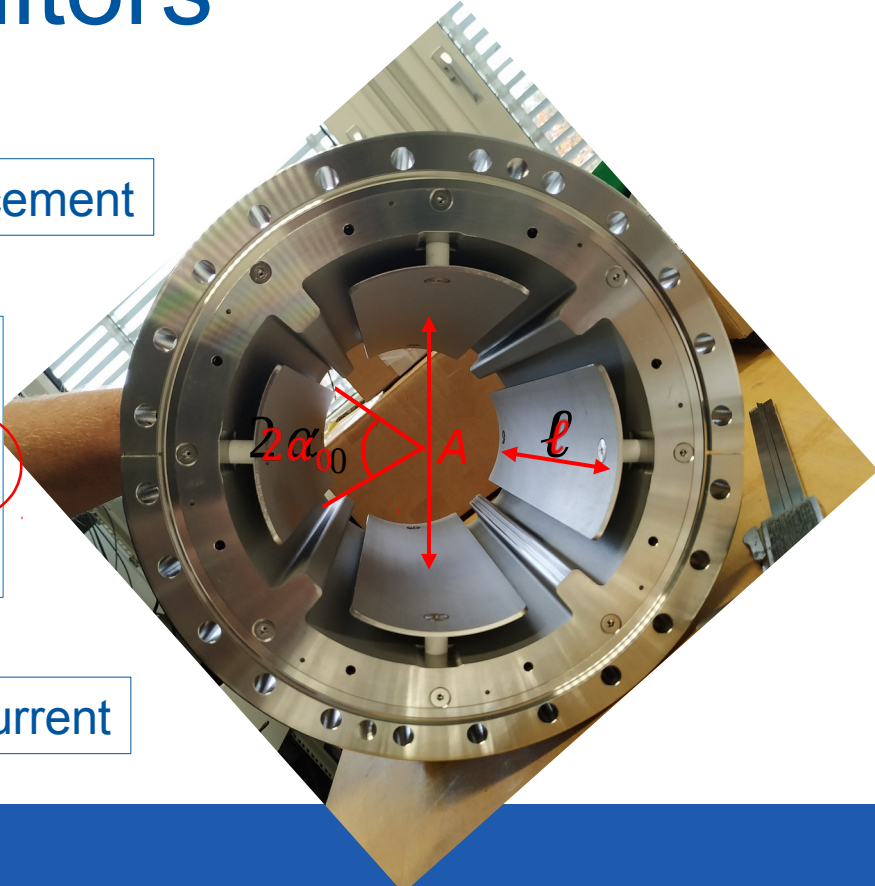
Beam Position Monitors

Electrode charge

Beam displacement

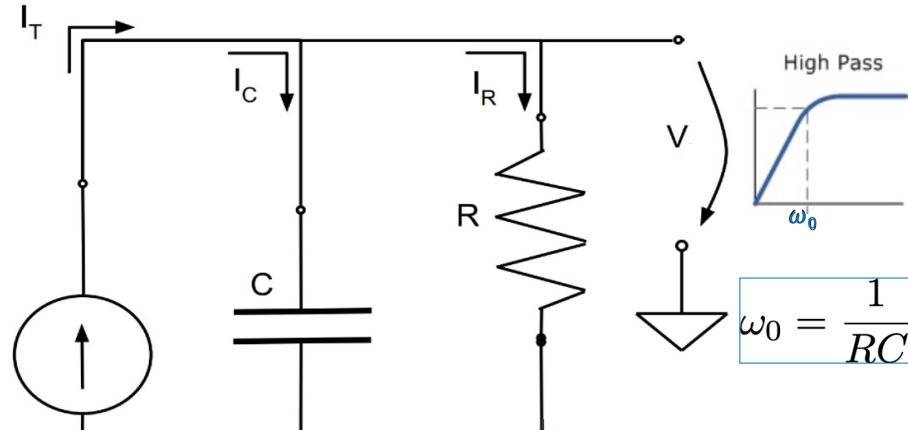
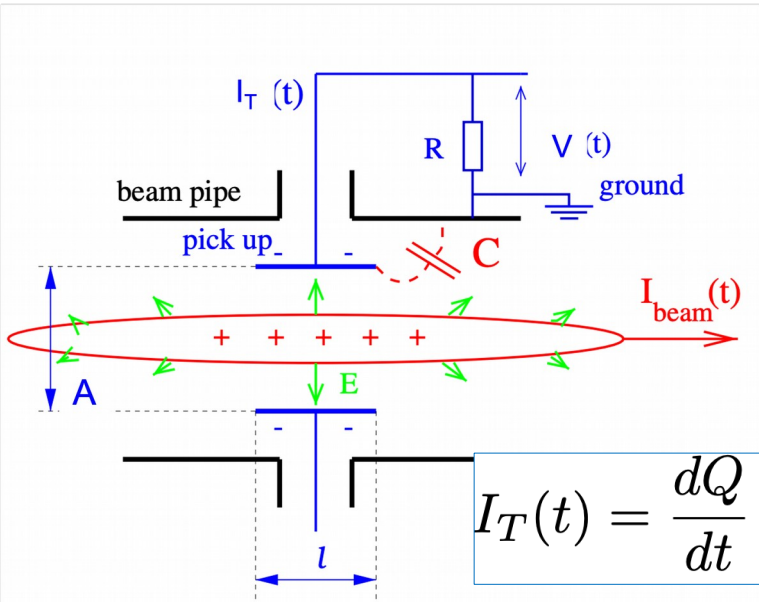
$$Q \approx \frac{\alpha_0 l A / 2}{\pi \beta c (A / 2 + \Delta d)} I_b$$

Beam current



The diagram shows a cross-section of a beam position monitor electrode assembly. It features a central circular opening with four curved electrodes arranged around it. Red arrows and labels indicate the geometry: $2\alpha_0$ is the angle subtended by the electrodes, A is the radius of the central opening, and l is the length of the electrodes.

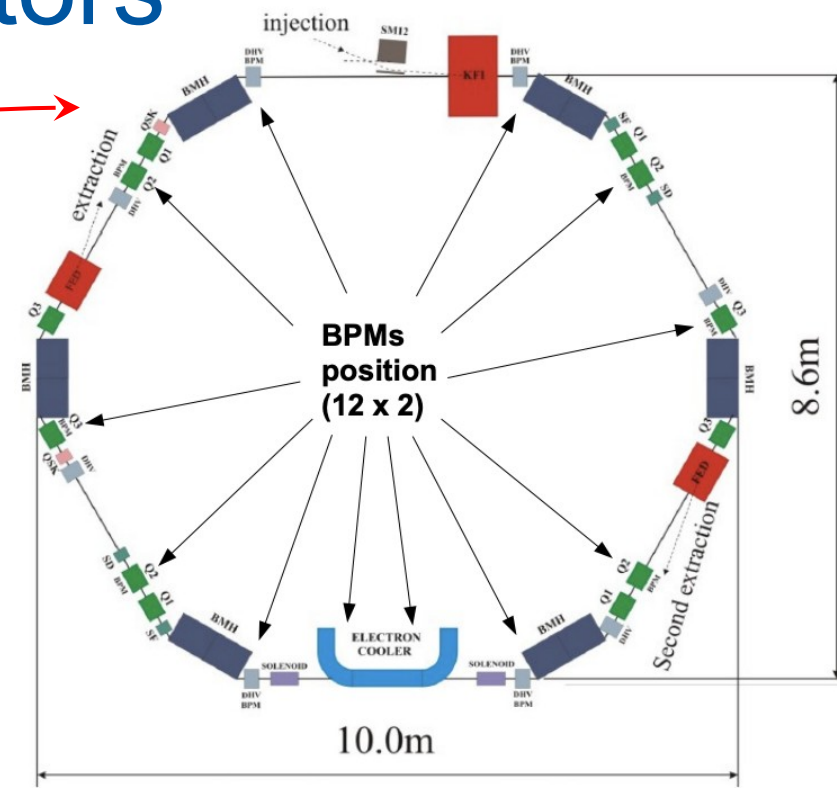
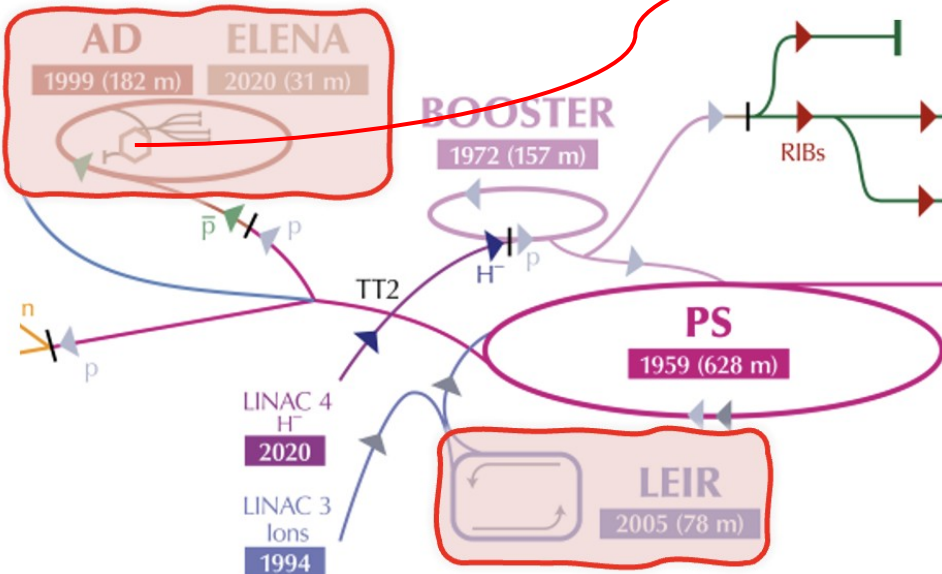
Beam Position Monitors



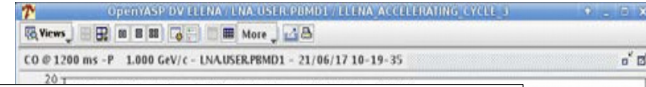
$$I_T(t) = \frac{dQ}{dt} \Rightarrow I_T(\omega) \approx j\omega \frac{\alpha_0 l A / 2}{\pi \beta c (A/2 + \Delta d)} I_b(\omega)$$

$$V(\omega) \approx \frac{1}{C} \frac{\omega^2 R^2 C^2 + j\omega RC}{1 + \omega^2 R^2 C^2} \frac{\alpha_0 l A / 2}{\pi \beta c (A/2 + \Delta d)} I_b(\omega)$$

Beam Position Monitors



Beam Position Monitors - ELENA



Momentum [MeV/c]
work, publisher, and DOI.

6th International Beam Instrumentation Conference
ISBN: 978-3-95450-192-2

IBIC2017, Grand Rapids, MI, USA

JACoW Publishing

doi:10.18429/JACoW-IBIC2017-TUPCF05

THE ORBIT MEASUREMENT SYSTEM FOR THE CERN EXTRA LOW ENERGY ANTIPROTON RING

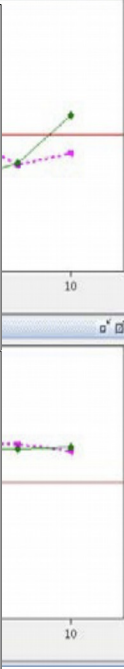
O. Marquersén[†], R. Ruffieux, L. Sørby, J. Molendijk, M.E. Angoletta, J. Quesada, M. Jaussi, CERN, Geneva, Switzerland

Proceedings of IBIC2022, Kraków, Poland

- Pre-Press Status 25-October 2022 -

AN LHC PROTECTION SYSTEM BASED ON FAST BEAM INTENSITY DROPS

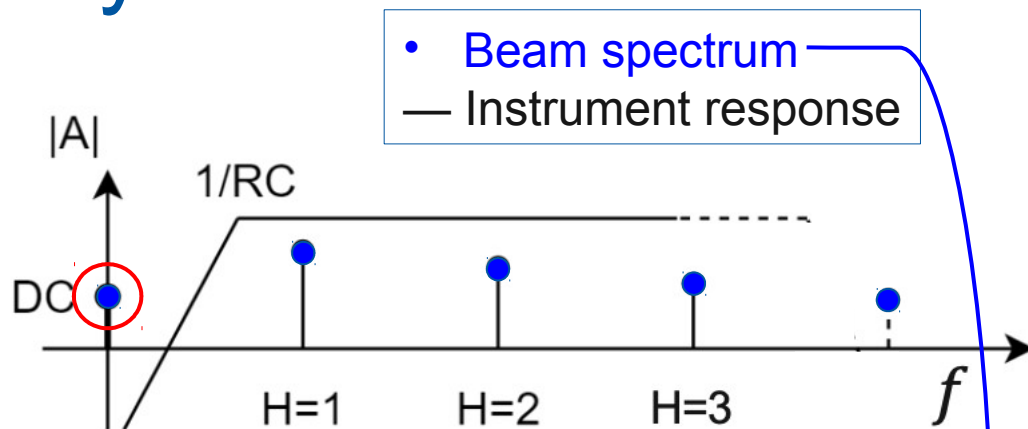
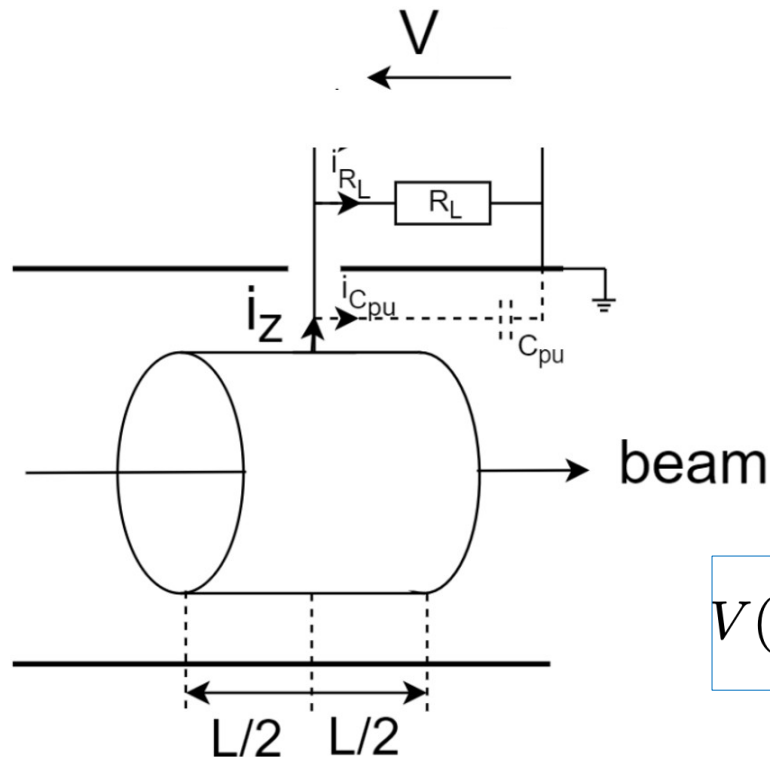
M. Gasior, T. Levens, CERN, Geneva, Switzerland



$\Delta d \approx$



BPM-based intensity

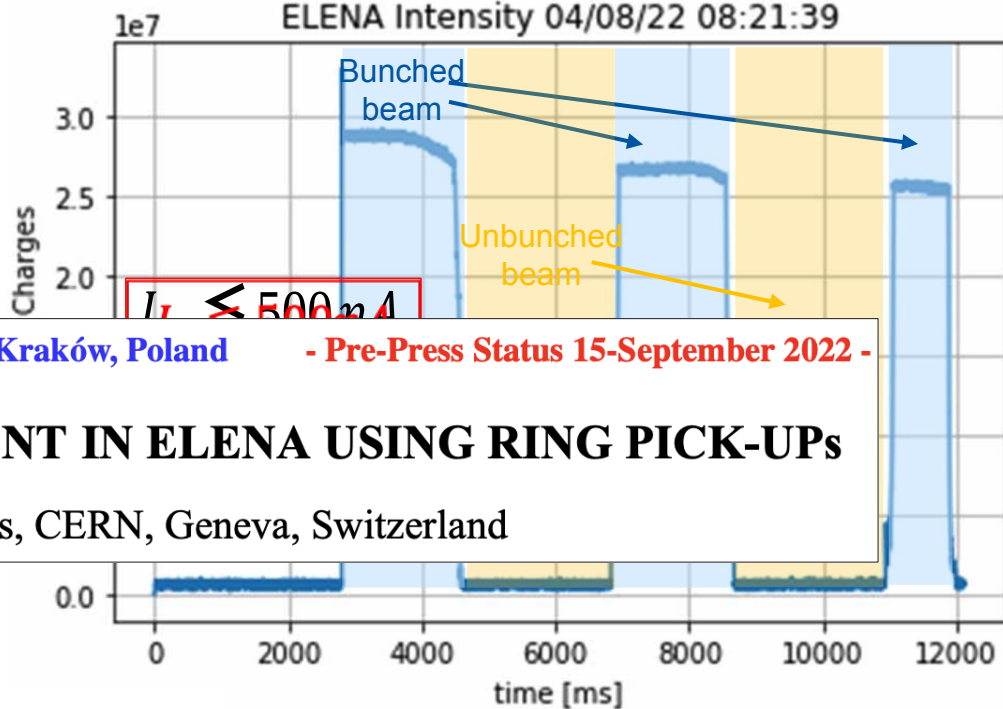
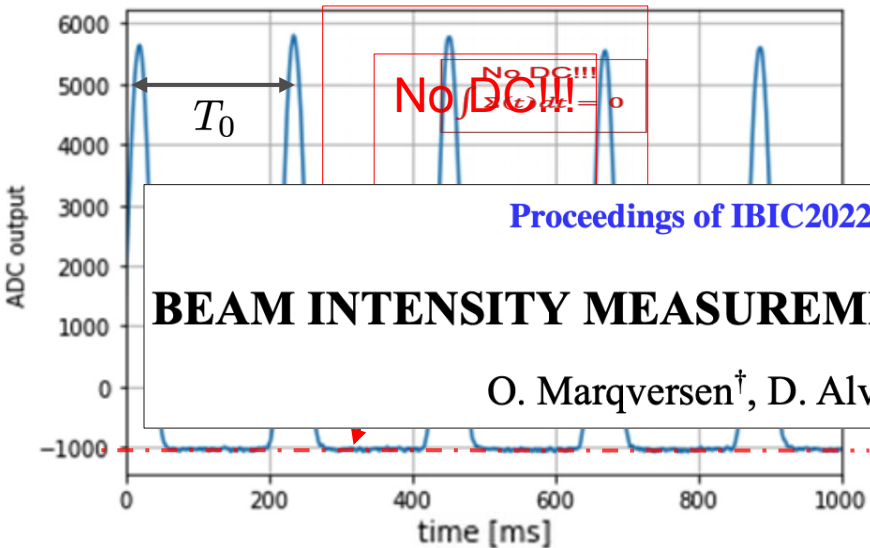


$$\omega \gg 1/(RC)$$

$$V(\omega) \approx \frac{1}{C} \frac{\omega^2 R^2 C^2 + j\omega RC}{1 + \omega^2 R^2 C^2} \frac{lA/2}{\beta c(A/2 + \Delta d)} I_b(\omega)$$

≈ 1

BPM-based intensity

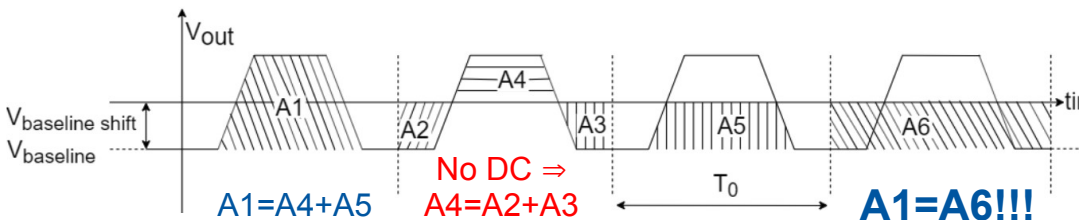


Proceedings of IBIC2022, Kraków, Poland

- Pre-Press Status 15-September 2022 -

BEAM INTENSITY MEASUREMENT IN ELENA USING RING PICK-UPS

O. Marquversen[†], D. Alves, CERN, Geneva, Switzerland

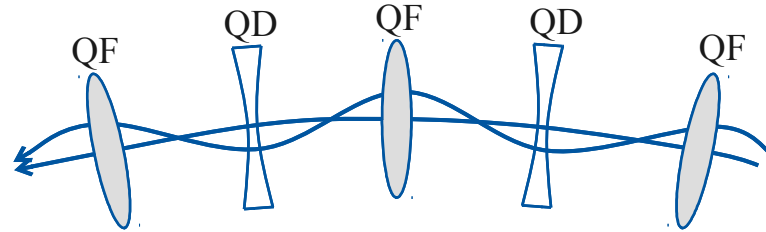
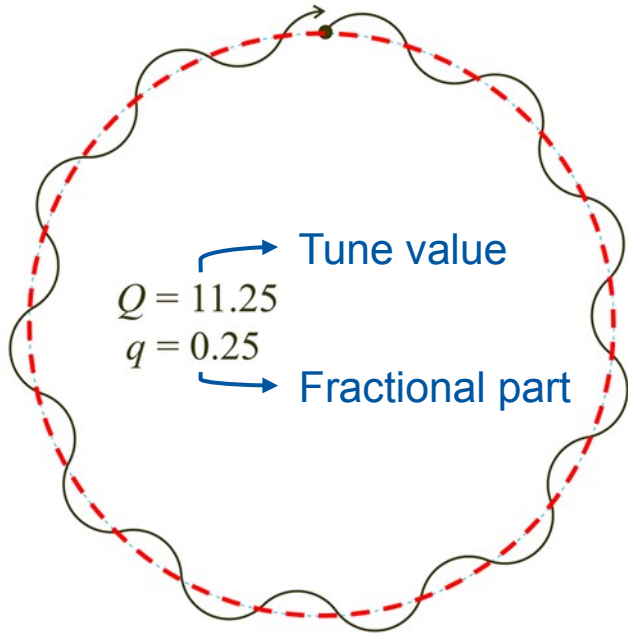


$$Q \approx C \frac{\beta c}{l} \int_0^{T_0} \Sigma(t) dt \approx C V_{baseline} \frac{L_{ring}}{l}$$

Beam intensity, β independent!!!

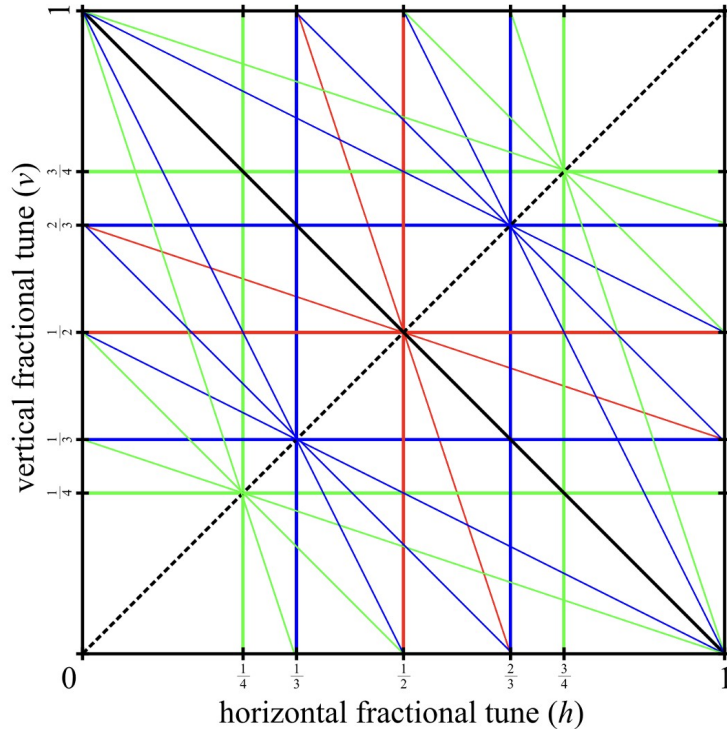
Tune monitors

Tune – what is it?



- Characteristic frequency of the magnetic lattice
- Given by the strength of the quadrupole magnets
- Defined as the number of transverse oscillations in a single turn
- Controlling the fractional part is crucial for beam stability

Tune - beam stability



Resonance condition:

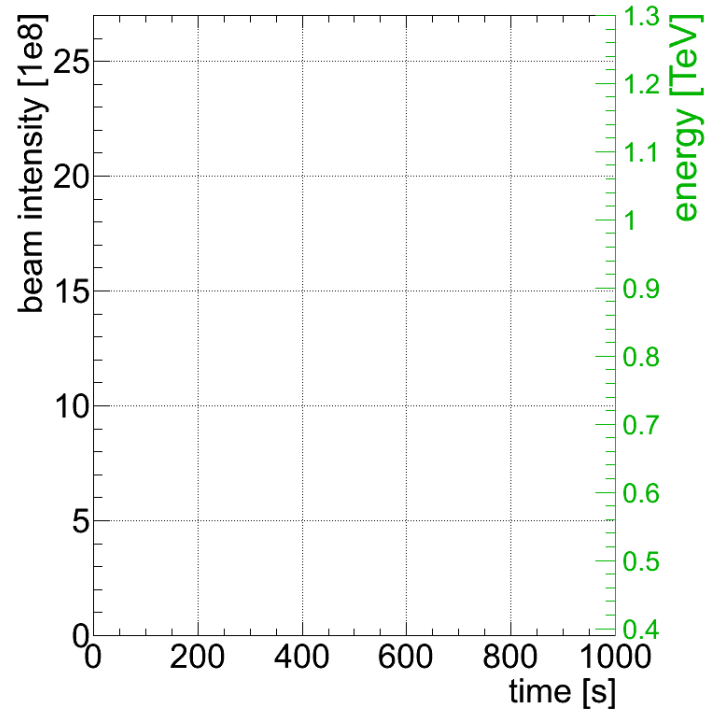
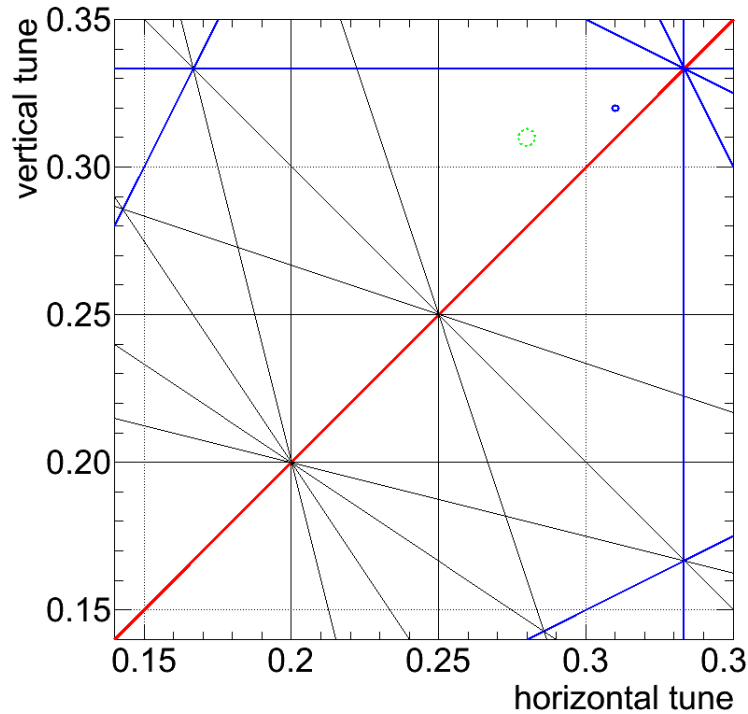
$$m h + n v = p$$

h, v - horizontal and vertical tunes

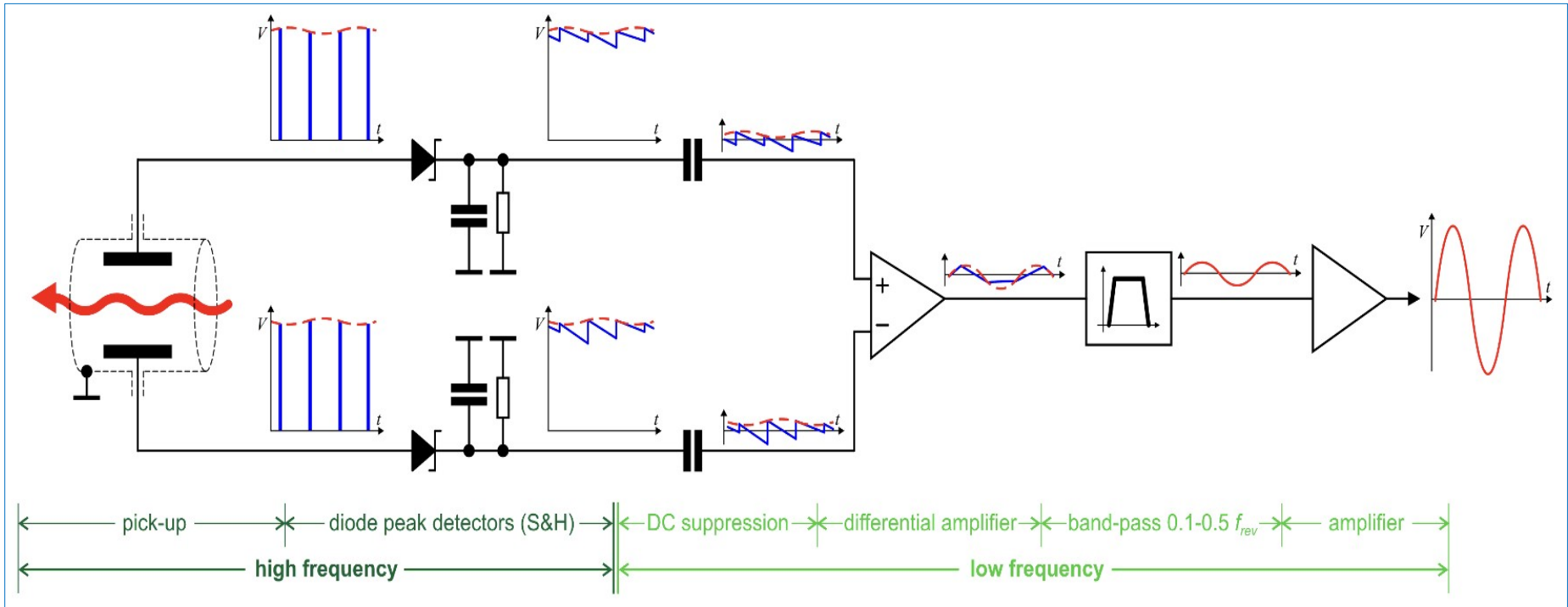
m, n, p - small integers

$|m| + |n|$ is the resonance order

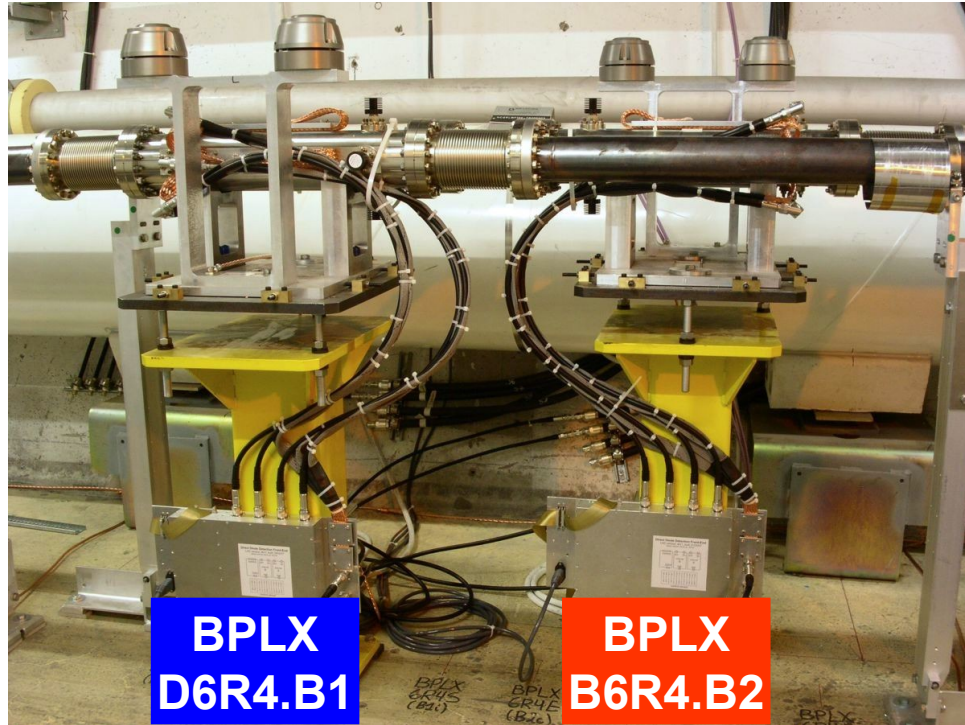
Tune – early energy ramps in the LHC



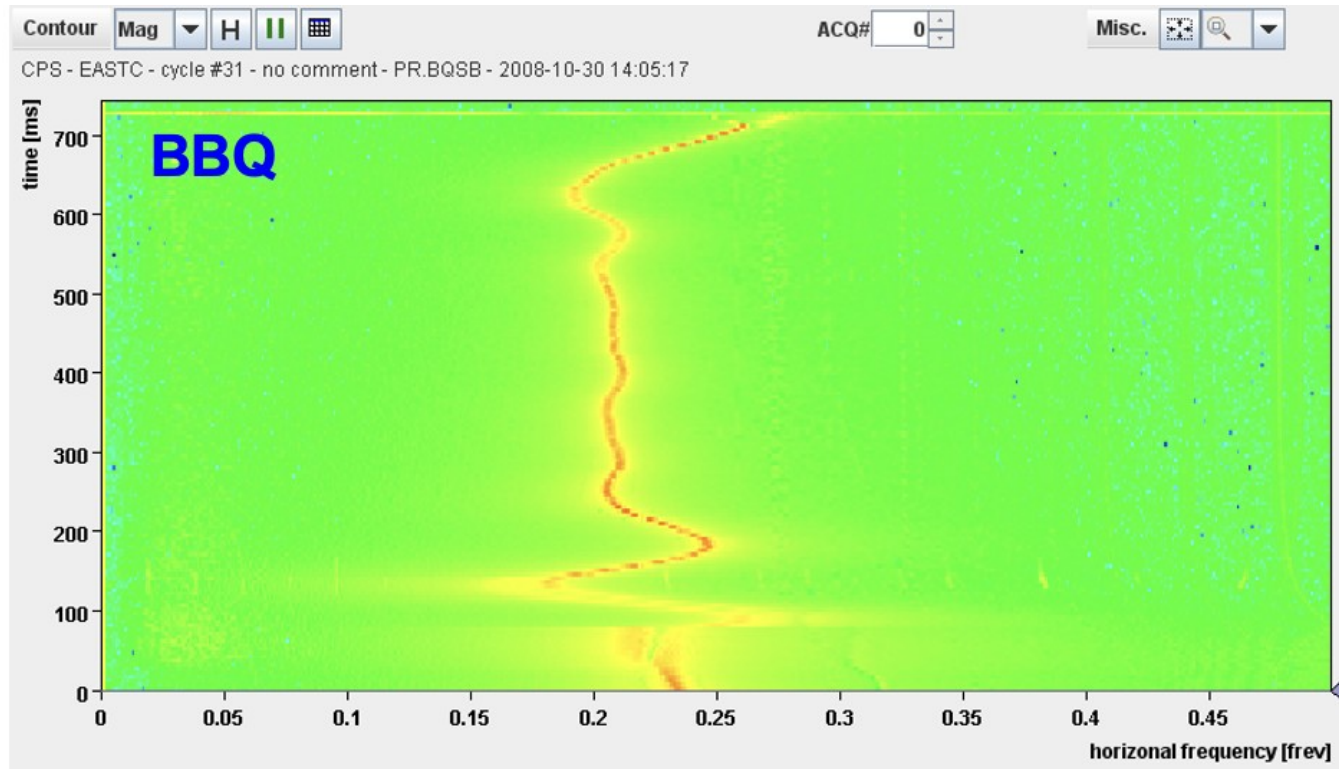
Tune – a beam position monitor with special electronics



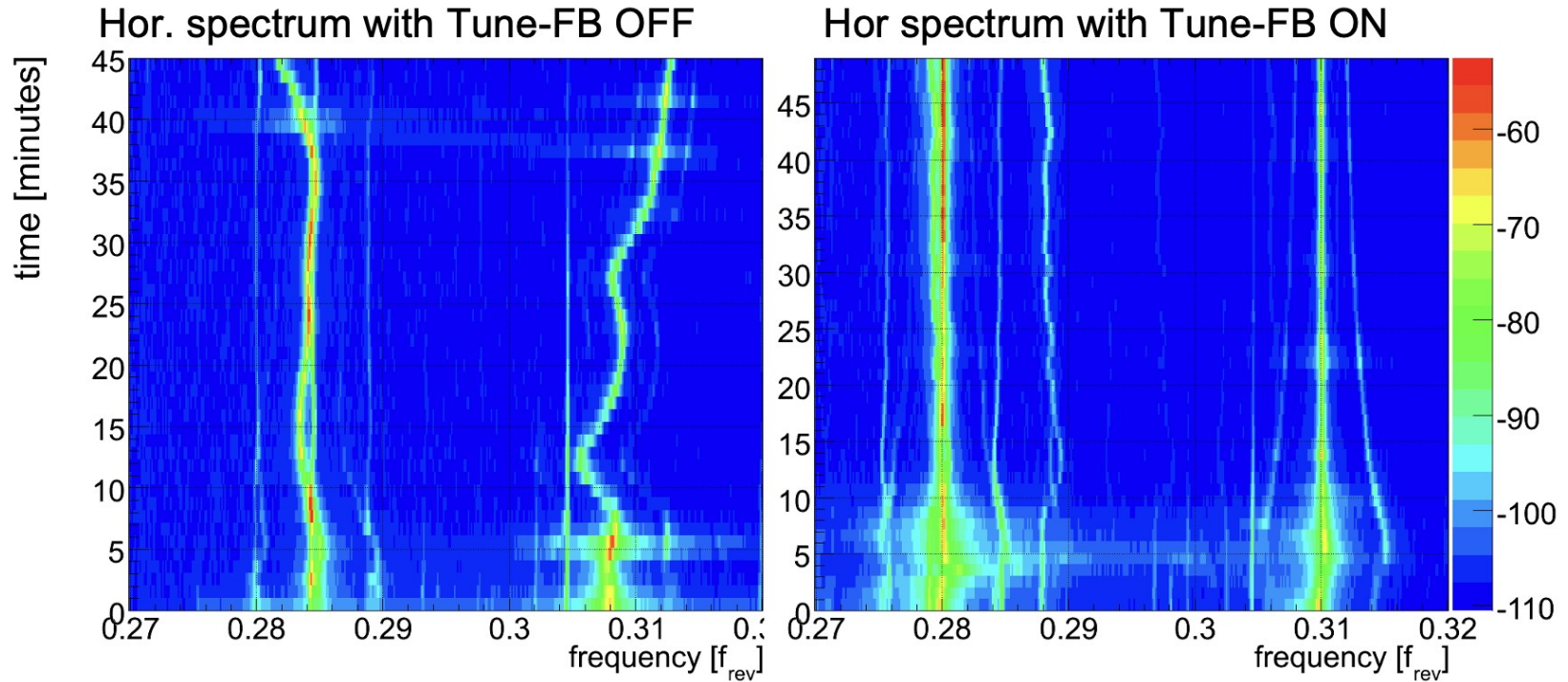
Tune – a beam position monitor with special electronics



Tune measurement in the PS ring

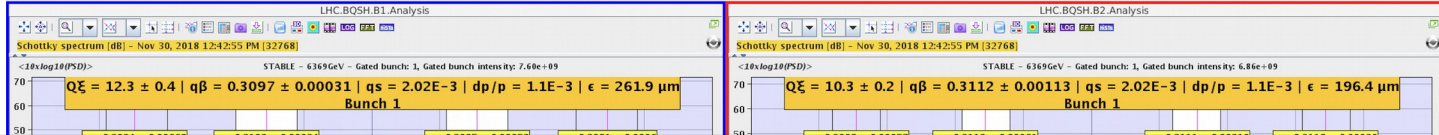


Tune feedback in the LHC



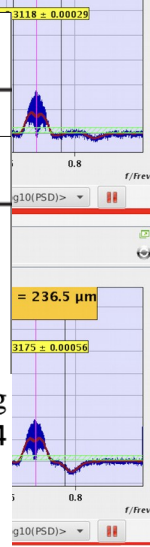
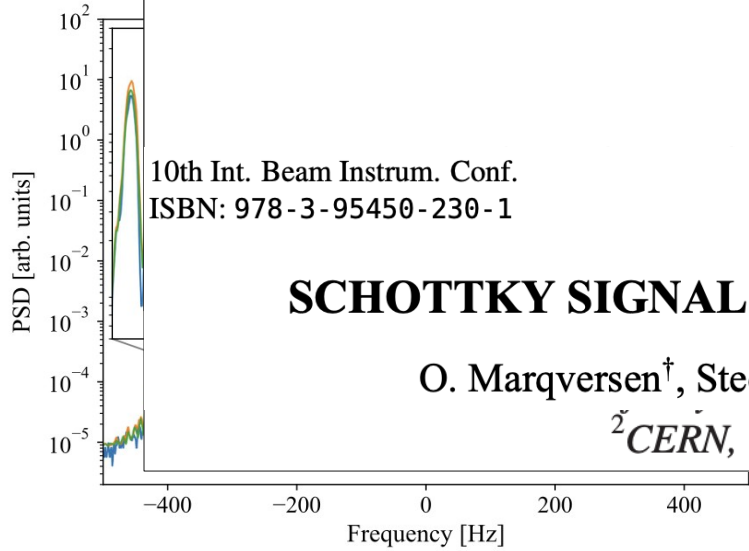
Potpourri of other instruments





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PHYSICAL REVIEW ACCELERATORS AND BEAMS **25**, 062801 (2022)



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ISSN: 2673-5350

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SCHOTTKY SIGNAL FROM DISTRIBUTED ORBIT PICK-UPS

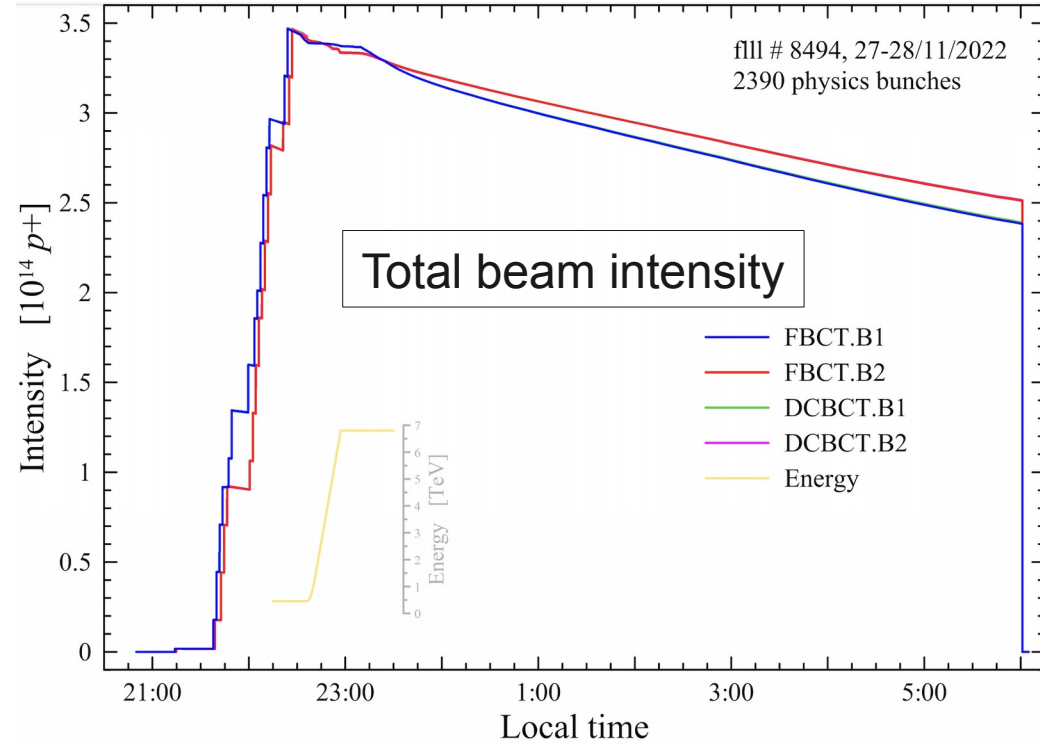
O. Marquers†, Steen Jensen, CERN-SY-BI, Geneve, Switzerland

²CERN, CH-1211 Geneva 23, Switzerland

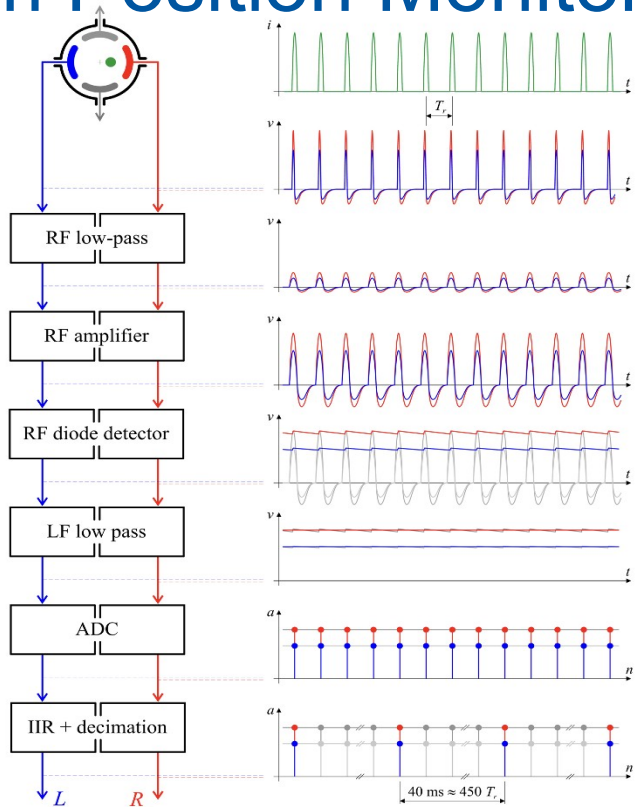
- Chromaticity
- Bunch shape

ne

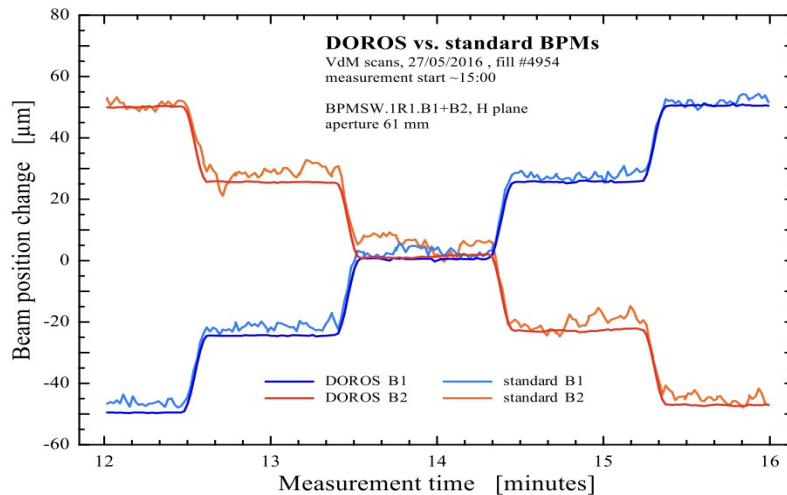
DC Beam Current Transformers



Beam Position Monitors with DOROS electronics

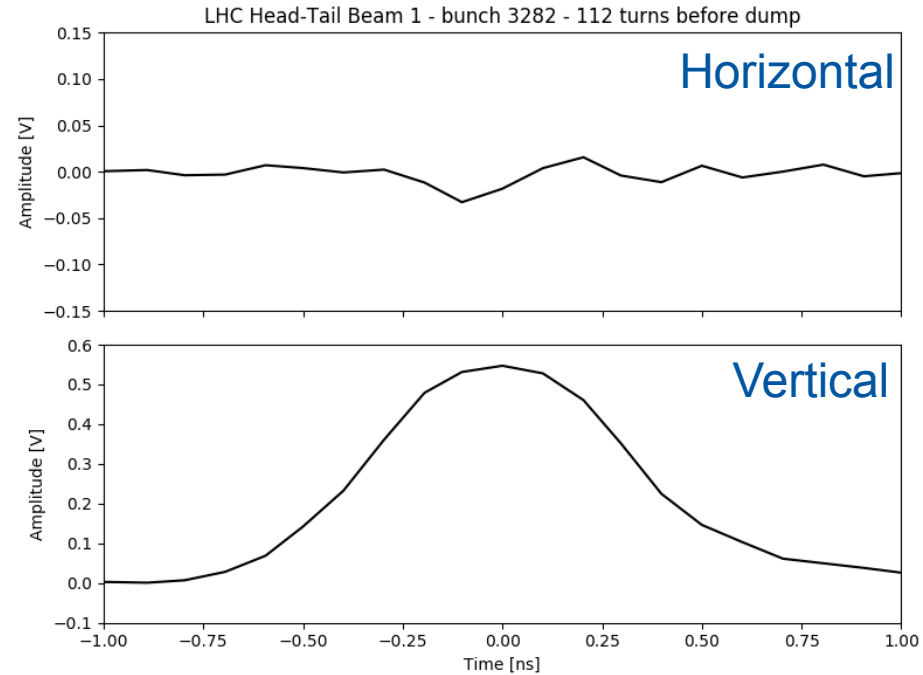
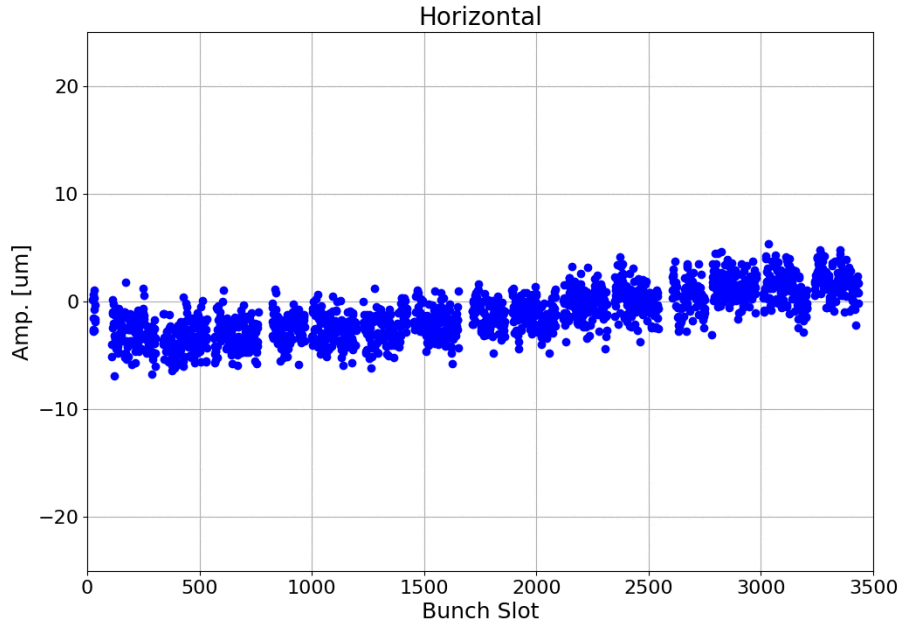


- Heavy analogue and digital filtering to reduce noise
- High resolution and therefore slow acquisition
- Beam resolution $\approx 0.1 \mu\text{m}$, accuracy $\approx 10 \mu\text{m}$
- Price to pay: 1 Hz measurement rate and one averaged position for all circulating bunches

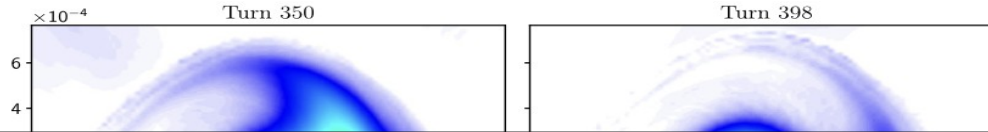


Head-tail beam position monitors

Fill: 6394, B2, Post Mortem, Turn before dump 100



Kalman filter – longitudinal phase space reconstruction

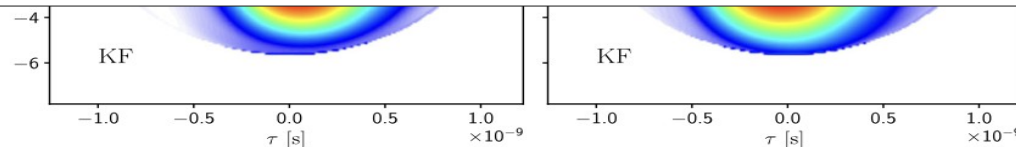


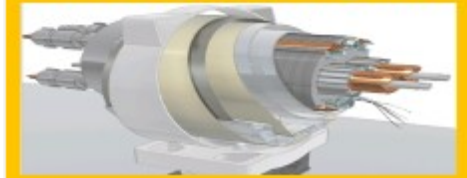
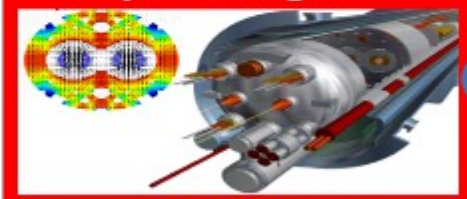
PHYSICAL REVIEW ACCELERATORS AND BEAMS **24**, 072801 (2021)

Kalman filter-based longitudinal phase-space reconstruction method for hadron machines

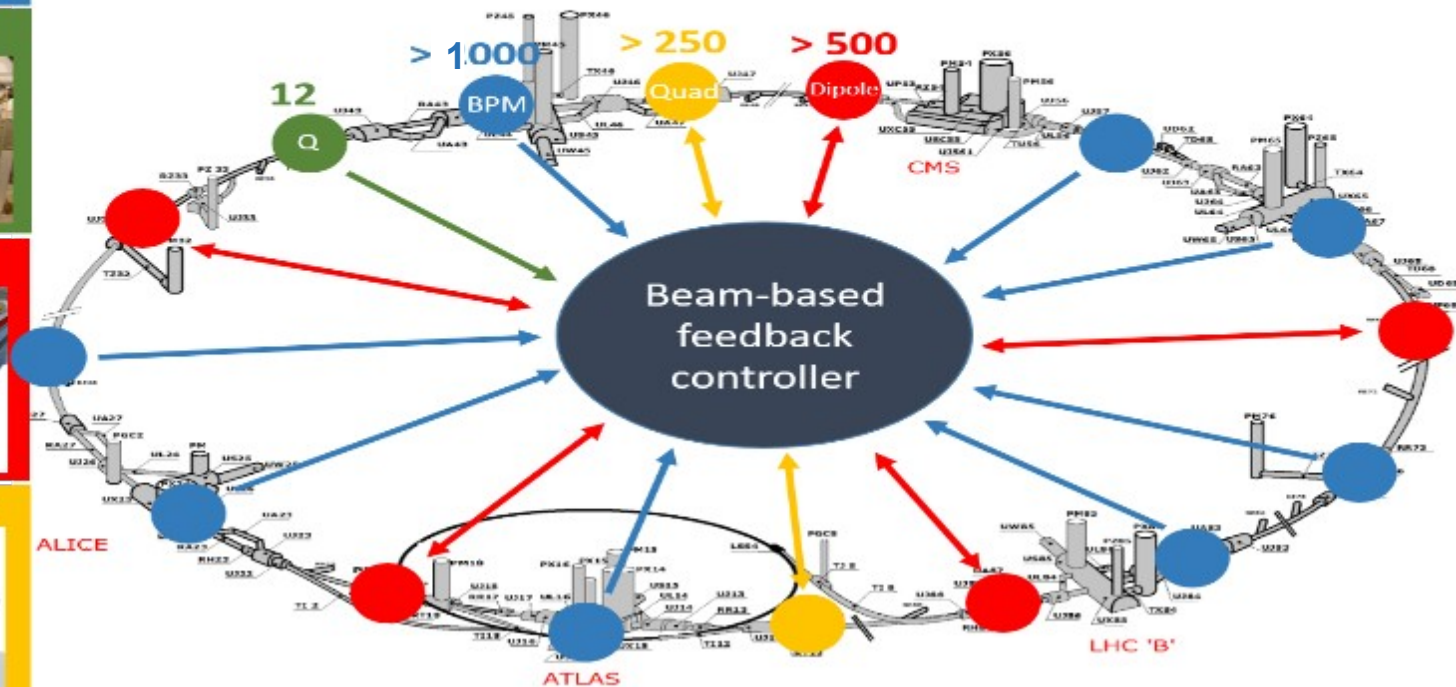
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LHC beam-based feedback system



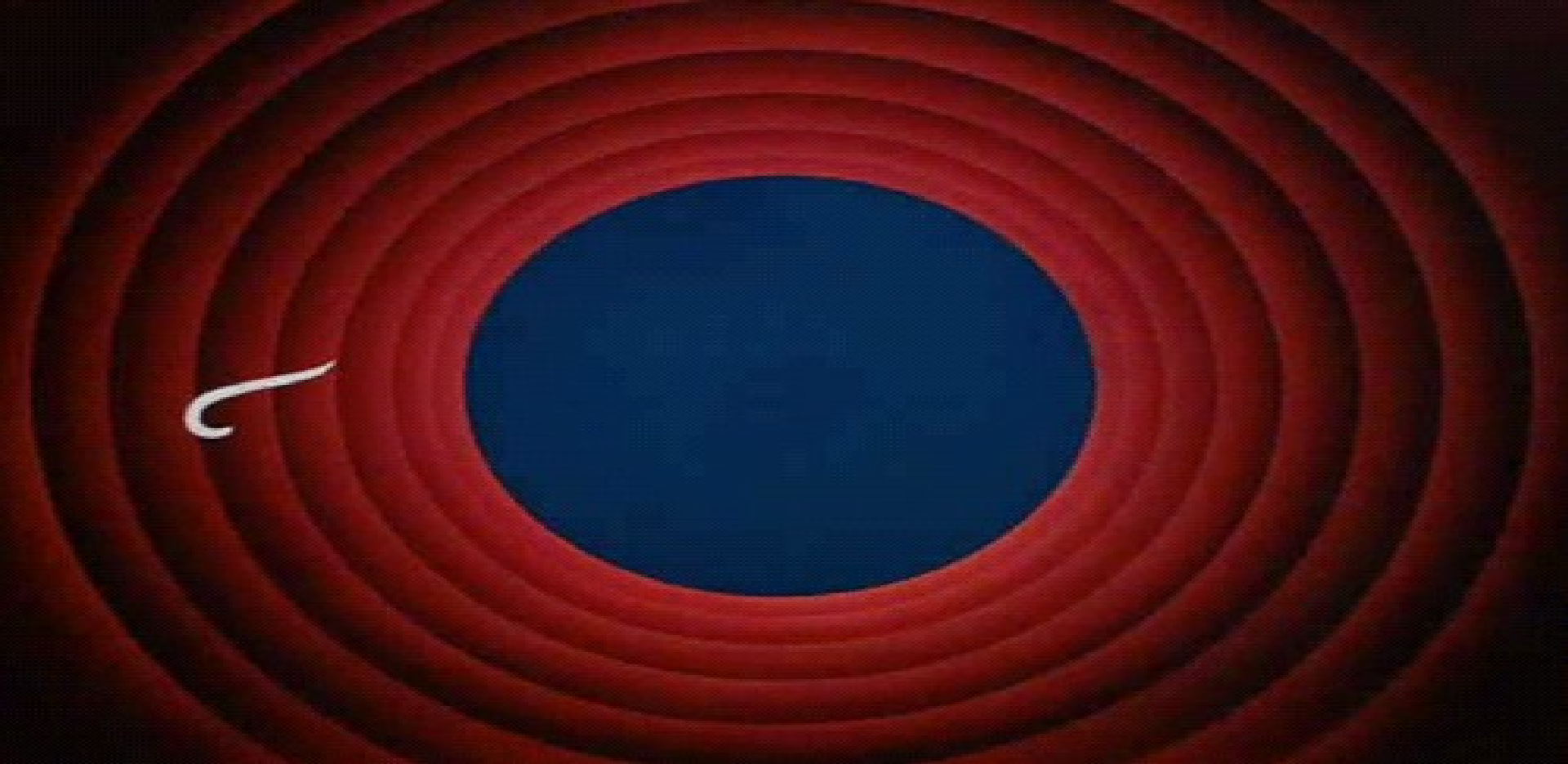
Material providers



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CERN SY-BI-IQ section



Spare slides

BPM-based intensity

- Simulation using finite element EM solvers (e.g. CST)
- Measured H pos independent of V offset
- Sum signal independent of beam offset (position)

